Least Squares Estimation of Large Dimensional Threshold Factor Models

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Abstract

This paper studies large dimensional factor models with threshold-type regime shifts in the loadings. We estimate the threshold by concentrated least squares, and factors and loadings by principal components. The estimator for the threshold is superconsistent, with convergence rate that depends on the time and cross-sectional dimensions of the panel, and it does not affect the estimator for factors and loadings: this has the same convergence rate as in linear factor models. We propose model selection criteria and a linearity test. Empirical application of the model shows that connectedness in financial variables increases during periods of high economic policy uncertainty.

JEL classification: C12, C13, C33, C52, G10.

Keywords: Large Threshold Factor Model, Least Squares Estimation, Model Selection, Linearity Testing, Connectedness.

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1 Introduction

Factor models are widely used tools to explain the common variations in large scale macroeconomic and financial data. An extensive literature analyzes factor models under the maintained assumption of constant loadings over the entire sample period: see Connor and Korajczyk (1986, 1988, 1993), Forni et al. (2000, 2004, 2015), Forni and Lippi (2001), Bai and Ng (2002), Stock and Watson (2002), and Bai (2003) for seminal contributions on linear factor models. Economic models are however unlikely to have constant parameters over time and factor models with time-dependent loadings are called for. Time-dependence in the loadings may be easily implemented through a change-point mechanism: this may be parameterized as either a structural break or a regime shift driven by the threshold principle, depending on the underlying data generating process.

Structural breaks in the loadings may arise as a consequence of events such as technological or policy changes. Several important contributions deal with large dimensional factor models subject to loadings instabilities. Breitung and Eickmeier (2011) show that ignoring breaks leads to overestimation of the number of factors and develop statistical tests for the null hypothesis of stability in the loadings. Bates et al. (2013) study the robustness properties of the principal components estimator of the factors under neglected loadings instability. Chen et al. (2014), Han and Inoue (2015) and Yamamoto and Tanaka (2015) develop further statistical tools to detect breaks. Chen (2015) considers least squares estimation of the break date. Cheng et al. (2015) propose shrinkage estimation of large dimensional factor models with structural breaks.

Regime shift representations of the dependent variables are suitable when "history repeats", as with financial returns (Timmermann (2008), and Ang and Timmermann (2012)). Ng and Wright (2013) introduce a threshold mechanism in large dimensional factor models to simulate data and investigate the effects of nonlinearities on business cycle dynamics1. We take Ng and Wright (2013) intuition as a starting point and propose a large dimensional factor model with regime changes in the loadings governed by the threshold principle. We let the threshold value be unknown and focus on estimation, model selection and linearity testing. To the very best of our knowledge, we are the first to tackle this problem.

Let $R^0$ be the true number of factors. Under the maintained assumption that $R^0$ is known, we propose to estimate the threshold value by concentrated least squares, and factors and loadings by

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1See Ng and Wright (2013), p. 1147.
principal components (Hansen (2000), and Bai and Ng (2002)). We obtain a number of novel theoretical results. Let \( N \) and \( T \) denote the cross-sectional and time series dimensions, respectively. We first provide sufficient conditions to ensure that our model is identified from a linear factor model: formally, for \( 0.5 < \alpha^0 \leq 1 \), we require that \( \text{at least} \) a fraction \( O\left(N^{\alpha^0}\right) \) of the \( N \) cross-sectional units experiences a regime shift in the loadings, so that the shift resists to the aggregation induced by the principal components estimator. We then show that the estimator for the threshold parameter is consistent at a rate equal to \( N^{\alpha^0}T \): this depends on the time series dimension \( T \) and the number of cross-sectional units \( N^{\alpha^0} \) subject to the threshold effect. The convergence rate monotonically increases in \( \alpha^0 \) and it is such that \( \sqrt{NT} < N^{\alpha^0}T \leq NT \): this shows the direct relationship between identification of the model and convergence rate of the estimator for the threshold. As a consequence of this superconsistency property, we finally show that the principal components estimator for both regime-specific loadings and factors have convergence rate equal to \( C_{NT} = \min \left\{ \sqrt{N}, \sqrt{T} \right\} \): despite the threshold effect, the convergence rate \( C_{NT} \) is equal to the one derived in Bai and Ng (2002) for linear factor models.

We next let the true number of factors \( R^0 \) be unknown so that it has to be estimated. Breitung and Eickmeier (2011) show that structural instability in the loadings leads to a factor representation with a higher dimensional factor space: due to an analogy argument, the same issue arises when a regime shift drives time variation in the loadings. Since the convergence rate \( C_{NT} \) of the estimator for loadings and factors is the same as in linear factor models, we make Bai and Ng (2002) information criteria robust to the threshold effect by accounting for the induced higher dimensional factor space representation.

As a last theoretical contribution, we propose a linearity test. Following Chen et al. (2014), and Han and Inoue (2015), we check whether the covariance matrix of the estimated factors is regime-dependent: we use the regression approach of Chen et al. (2014) and extend Hansen (1996) seminal contribution to derive the asymptotic distribution of the test statistic under the null hypothesis of linearity.

We finally show how our theoretical framework may be used to measure connectedness in financial markets (Acharya et al. (2010), Billio et al. (2012), Engle and Kelly (2012), Diebold and Yilmaz (2014), and Adrian and Brunnermeier (2016)). We extend Billio et al. (2012) measure based on principal components analysis to allow for regime-specific connectedness. Using Baker et al. (2016) index of economic policy uncertainty as threshold variable, we show that connectedness in financial markets increases during periods of high uncertainty: this may be relevant for risk measurement and management.
The remainder of the paper is organized as follows. Section 2 describes the model. Section 3 deals with estimation. Section 4 looks at model selection. Section 5 develops a linearity test. Section 6 performs a Monte Carlo analysis. Section 7 provides an empirical application. Section 8 outlines directions for future research. Finally, Section 9 concludes. Appendix A provides technical proofs.

Concerning notation, \(\mathbb{I}(\cdot)\) denotes the indicator function; given a square matrix \(A\), \(\text{tr}\,(A)\) denotes the trace of \(A\); the norm of a generic matrix \(A\) is \(\|A\| = [\text{tr}\,(A'A)]^{1/2}\); for a given scalar \(A\), \(|A|\), \(I_A\) and \(0_A\) are the absolute value of \(A\), the \(A \times A\) identity matrix and the zero matrix, respectively; \(\xrightarrow{p}\) denotes convergence in probability; \(\xrightarrow{d}\) denotes convergence in distribution; \(\Rightarrow\) denotes weak convergence with respect to the uniform metric.

2 The Approximate Threshold Factor Model

We consider the model

\[
x_t = \mathbb{I}(z_t \leq \theta) A_1 f_t + \mathbb{I}(z_t > \theta) A_2 f_t + \epsilon_t, \quad t = 1, \ldots, T, \tag{1}
\]

where \(T\) denotes the time series dimension of the available sample; \(x_t = (x_{1t}, \ldots, x_{Nt})' \in \mathbb{R}^N\) is the \(N \times 1\) vector of observable dependent variables; \(f_t = (f_{1t}, \ldots, f_{Rt})' \in \mathbb{R}^R\) is the \(R \times 1\) vector of latent factors; \(z_t \in \mathbb{R}\) is an observable covariate and \(\theta\) is the unknown threshold value; \(\epsilon_t = (\epsilon_{1t}, \ldots, \epsilon_{Nt})' \in \mathbb{R}^N\) is the \(N \times 1\) vector of idiosyncratic errors; \(\Lambda_j = (\lambda_{j1}, \ldots, \lambda_{jN})' \in \mathbb{R}^N\) is the \(N \times R\) matrix of factor loadings with \(i - \text{th}\) row defined as \(\lambda_{ji} = (\lambda_{j1i}, \ldots, \lambda_{jiR})'\), for \(j = 1, 2\) and \(i = 1, \ldots, N\).

The model in (1) belongs to the class of threshold models proposed in Tong and Lim (1980): see Tsay (1989, 1998), Chan (1993) and Hansen (1996, 1999, 2000) for methodological contributions; and Hansen (2011) for a survey of the literature. According to the threshold principle introduced in Pearson (1900), the regime prevailing at time \(t\) depends on the position of \(z_t\) with respect to the unknown threshold \(\theta\).

Ng and Wright (2013) simulate data from a large dimensional threshold factor model to investigate the effects of nonlinearities on business cycle dynamics\(^2\): we explicitly focus on estimation, model selection and linearity testing. Our results extend to the case in which the threshold variable is more generally defined as a linear combination of covariates (Massacci (2014)): this would be relevant when the driver

\(^2\)See Ng and Wright (2013), p. 1147.
of the regimes is not \textit{a priori} known.

The model in (1) extends large dimensional linear factor models to allow for a threshold effect on the loadings. Given Assumption C3 stated in Section 3.1 below, we follow Chamberlain and Rothschild (1983) and allow for some degree of correlation in the idiosyncratic components within each regime: (1) then is an \textit{approximate threshold factor model}; it is more general than an \textit{exact threshold factor model}, which would extend the arbitrage pricing theory of Ross (1976) and would not allow for any correlation in the idiosyncratic components in any regime.

3 Estimation

As in Stock and Watson (2002), we study estimation of (1) under the assumption that the true number of factors $R^0$ (i.e., the true dimension of $f_t$) is known. We extend the theory in Bai and Ng (2002) based on principal components estimation to allow for concentrated least squares estimation, as motivated in Hansen (2000) for threshold regressions. The plan is as follows: Section 3.1 states the assumptions; Section 3.2 deals with identification; Section 3.3 describes the principal components estimator; Section 3.4 proves the consistency of the estimator; and Section 3.5 derives the convergence rates.

3.1 Assumptions

We group the assumptions into three sets, depending on the role they play to identify and estimate the model, and to derive the convergence rates. Let $\mathbb{I}_{1t}(\theta) = \mathbb{I}(z_t \leq \theta)$ and $\mathbb{I}_{2t}(\theta) = \mathbb{I}(z_t > \theta)$. For $j = 1, 2$, denote $\mathbf{A}_j^0 = (\mathbf{\lambda}_{j1}^0, \ldots, \mathbf{\lambda}_{jN}^0)'$, $\mathbf{\theta}^0$ and $\mathbf{f}_t^0$ the true values of $\mathbf{A}_j$, $\mathbf{\theta}$ and $\mathbf{f}_t$, respectively. Define $\mathbf{f}_{jt}^0(\theta) = \mathbb{I}_{jt}(\theta)\mathbf{f}_t^0$, for $j = 1, 2$ and $t = 1, \ldots, T$, and let $\mathbf{\delta}_i^0 = \mathbf{\lambda}_{2i}^0 - \mathbf{\lambda}_{1i}^0$, for $i = 1, \ldots, N$.

3.1.1 Identification

Assumption I - Threshold Factor Model. For $0.5 < \alpha^0 < 1$, $\mathbf{\delta}_i^0 \neq \mathbf{0}$ for $i = 1, \ldots, N^{\alpha^0}$, and

$$\sum_{i=N^{\alpha^0}+1}^{N} \mathbf{\delta}_i^0 = O(1).$$

Assumption I requires that at least a fraction $O\left(N^{\alpha^0}\right)$ of the $N$ series experiences a threshold effect, for $0.5 < \alpha^0 < 1$: this follows up on Bates \textit{et al}. (2013), who show that if at most $O\left(N^{0.5}\right)$ series undergo a break then the principal components estimator as applied to the misspecified linear model achieves the same Bai and Ng (2002) convergence rate. Assumption I ensures that enough series experience a regime
shift so that (1) is identified from a linear factor model when factors and loadings are estimated by principal components. As shown in Theorem 3.4 below, \( \alpha^0 \) affects the convergence rate of the estimator for \( \theta^0 \): the higher the former, the faster the latter. In this paper we do not aim at estimating \( \alpha^0 \) and leave this interesting issue to future research.

### 3.1.2 Consistency

**Assumption C1 - Factors.** \( \mathbb{E} \| f^0_t \|^4 < \infty \); for \( j = 1, 2, T^{-1} \sum_{t=1}^{T} f^0_{jt} (\theta) f^0_{jt} (\theta^0)^T \xrightarrow{P} \Sigma^0_{jt} (\theta, \theta^0) \) as \( T \to \infty \) for all \( \theta \) and some positive definite matrix \( \Sigma^0_{jt} (\theta, \theta^0) \).

**Assumption C2 - Factor Loadings.** For \( j = 1, 2 \) and \( i = 1, \ldots, N \), \( \| \lambda^0_{ji} \| \leq \bar{\lambda} < \infty \), and \( \| \Lambda^0_j \Lambda^0_j / N - D^0_{\Lambda, j} \| \to 0 \) as \( N \to \infty \) for some \( R^3 \times R^3 \) positive definite matrix \( D^0_{\Lambda, j} \).

**Assumption C3 - Time and Cross-Section Dependence and Heteroskedasticity.** There exists a positive \( M < \infty \) such that for all \( \theta \) and for all \((N,T)\),

(a) \( \mathbb{E} (e_{it}) = 0 \) and \( \mathbb{E} |e_{it}|^8 \leq M; \)

(b) \( \mathbb{E} \left[ \| j_{it} (\theta) \| j_{it} (\theta) e_{it} e_{it} \right] = \tau_{jitv} (\theta) \) with \( |\tau_{jitv} (\theta)| \leq |\tau_{jitv}| \) for some \( \tau_{jitv} \), and for all \( i, \) and \( T^{-1} \sum_{t=1}^{T} \sum_{v=1}^{T} |\tau_{jitv}| \leq M; \)

(c) \( \mathbb{E} \left[ T^{-1} \sum_{t=1}^{T} \oslash j_{it} (\theta) e_{it} e_{it} \right] = \sigma_{jit}(\theta), \ |\sigma_{jit}(\theta)| \leq M \) for all \( l \), and \( N^{-1} \sum_{i=1}^{N} \sum_{t=1}^{T} |\sigma_{jit}(\theta)| \leq M; \)

(d) \( \mathbb{E} \left[ T^{-1/2} \sum_{t=1}^{T} \oslash j_{it} (\theta) e_{it} e_{it} - \mathbb{E} \left[ \oslash j_{it} (\theta) e_{it} e_{it} \right] \right]^4 \leq M \) for every \((i,l)\).

**Assumption C4 - Weak Dependence between \( f^0_t, z_t \) and \( e_{it} \).** There exists some positive constant \( M < \infty \) such that for all \( \theta \) and for all \((N,T)\),

\[
\mathbb{E} \left\{ N^{-1} \sum_{i=1}^{N} \left\| T^{-1/2} \left[ \sum_{t=1}^{T} \oslash j_{it} (\theta) f^0_t e_{it} \right] \right\|^2 \right\} \leq M, \quad j = 1, 2.
\]

Assumptions C1 to C4 are the natural extensions of Assumptions A to D imposed on linear factor models in Bai and Ng (2002) and accommodate the threshold effect. Assumption C1 restricts the sequences \( \{ f^0_t \}_{t=1}^{T} \) and \( \{ z_t \}_{t=1}^{T} \) so that appropriate second moments exist; it also imposes a full rank condition that excludes multicollinearity in the factors. According to Assumption C2, factor loadings are nonstochastic and each factor has a nonnegligible effect on the variance of \( x_t \) within each regime.
Under Assumption C3, limited degrees of time-series and cross-section dependence in the idiosyncratic components as well as heteroskedasticity are allowed. Finally, Assumption C4 provides an upper bound to the degree of dependence between the factors, \( z_t \) and the idiosyncratic components: Assumption C4 is stronger than Assumption D in Bai and Ng (2002), which only bounds the dependence between the factors and the idiosyncratic components. Although we deal with a panel structure, we do not require the threshold variable \( z_t \) to be strictly exogenous as in Assumption 2 in Hansen (1999): in particular, \( z_t \) is allowed to be predetermined and equal to some lagged value of one of the elements of \( x_t \).

### 3.1.3 Convergence Rates

Define \( \hat{D}_f^0 (\theta) = \mathbb{E} (f_i^0 | \zeta_t = \theta) \) and denote by \( f_z (z_t) \) the density function of \( z_t \).

**Assumption CR - Stationarity, Moment Bound, Continuity and Full Rank.**

(a) \( \{f_i^0, z_t, e_t\}_{t=1}^T \) is strictly stationary, ergodic and \( \rho \)-mixing, with \( \rho \)-mixing coefficients satisfying \( \sum_{m=1}^{\infty} \rho_m^{1/2} < \infty \);

(b) For all \( \theta \), \( \mathbb{E} \left( \left\| f_i^0 c_t \right\|^4 \mid z_t = \theta \right) \leq C \) and \( \mathbb{E} \left( \left\| f_i^0 \right\|^4 \mid z_t = \theta \right) \leq C \) for some \( C < \infty \) and for \( i = 1, \ldots, N \), and \( f_z (\theta) \leq \hat{f} < \infty \);

(c) \( f_z (\theta) \) and \( D_f^0 (\theta) \) are continuous at \( \theta = \theta^0 \);

(d) \( \delta_i^0 D_f^0 (\theta^0) \delta_i^0 > 0, i = 1, \ldots, N^{\alpha^0} \) and \( 0.5 < \alpha^0 < 1 \), and \( \sum_{i=N^{\alpha^0}+1}^{N} \delta_i^0 D_f^0 (\theta^0) \delta_i^0 = O(1) \);

\( f_z (\theta) > 0 \) for all \( \theta \).

Assumption CR is analogous to Assumption 1 in Hansen (2000). Assumption CR(a) restricts the memory of the sequence \( \{f_i^0, z_t, e_t\}_{t=1}^T \); it excludes trends and integrated processes. Assumption CR(b) gives conditional moment bounds. Assumption CR(c) imposes a continuous support on \( z_t \). The full-rank condition in Assumption CR(d) strengthens Assumption I and rules out the "continuous threshold" set up of Chan and Tsay (1998), which arises in the one-factor model when the scalar factor \( f_i^0 \) equals the threshold variable \( z_t \) and \( \theta^0 = 0 \): in this case, \( \delta_i^0 \mathbb{E} (f_i^0 f_i^0 \mid z_t = \theta^0) \delta_i^0 = \delta_i^0 \mathbb{E} (f_i^0 f_i^0 \mid f_i^0 = \theta^0) \delta_i^0 = 0 \), for \( i = 1, \ldots, N \), and Assumption CR(d) is violated.
3.2 Identification

Let \( \Delta^0 = (\delta_0^1, \ldots, \delta_N^0) \)' and write the data generating process of \( x_t \) as \( x_t = \Lambda^0 \mathbf{f}_t^0 + \mathbf{I}_2 (\theta^0) \Delta^0 \mathbf{f}_t^0 + \mathbf{e}_t \). Define \( \mathbf{F}^0 = (\mathbf{f}_1^0, \ldots, \mathbf{f}_N^0) \) and denote \( \tilde{\mathbf{A}}_1 = (\tilde{\lambda}_{11}, \ldots, \tilde{\lambda}_{1N}) \)' the principal components estimator for \( \Lambda_1^0 \) from the misspecified linear factor model \( x_t = \Lambda_1 \mathbf{f}_t + \mathbf{e}_t \). Let \( \tilde{\mathbf{V}}_1 \) be the \( R_0 \times R_0 \) diagonal matrix of the first \( R_0 \) largest eigenvalues of \( \tilde{\Sigma}_x = (NT)^{-1} \sum_{t=1}^{T} x_t x_t' \) in decreasing order: the underlying optimization problem requires the normalization \( N^{-1} \tilde{\mathbf{A}}_1' \tilde{\mathbf{A}}_1 = \mathbf{I}_{R_0} \). The following theorem states the properties of \( \tilde{\mathbf{A}}_1 \).

Theorem 3.1 There exists a \( R_0 \times R_0 \) rotation matrix \( \tilde{\mathbf{H}}_1 \) with rank \( \tilde{\mathbf{H}}_1 = R_0 \) such that

\[
B_{NT}^2 \left( \frac{1}{N} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} - \tilde{\mathbf{H}}_1 \lambda_{1i}^0 \right\|^2 \right) = O_p(1),
\]

as \( N, T \to \infty \), where

\[
B_{NT} = \min \left\{ \sqrt{N}, \sqrt{T}, N^{1-\alpha^0} \right\}
\]

and

\[
\tilde{\mathbf{H}}_1 = \frac{\mathbf{F}^0 \mathbf{F}^0'}{T} \Lambda_1^0 \tilde{\mathbf{A}}_1 \frac{\tilde{\mathbf{V}}_1^{-1}}{N}.
\]

Theorem 3.1 shows that the average squared deviations between the loadings estimated using a linear factor model and those that lie in the true loading space vanish as \( N, T \to \infty \) at a rate equal to \( B_{NT}^2 \), which drives identification. Under Assumption I, the model in (1) is identified from the linear factor model as the rate of convergence \( N^{1-\alpha^0} \) of the principal components estimator is slower than it would be under correct linear model specification: the model in (1) would not be identified from a linear factor model if \( 0 \leq \alpha^0 \leq 0.5 \), since in this case \( B_{NT}^2 = \min \{ N, T \} \), as derived in Bai and Ng (2002). If \( \alpha^0 = 1 \) and all cross-sectional units are subject to threshold effect, \( B_{NT}^2 = 1 \) and the principal components estimator from the misspecified linear model is asymptotically biased. As proved in Theorem 3.4, the parameter \( \alpha^0 \) regulates the convergence rate of the estimator for the unknown threshold value \( \theta^0 \): this result shows the connection between identification strength and estimation precision.

3.3 Principal Components Estimation

We estimate factors and loadings by principal components, and \( \theta^0 \) by concentrated least squares: see Bai and Ng (2002) and Hansen (2000), respectively. Define the \( N \times 2R_0 \) matrix of loadings \( \mathbf{A} = (\mathbf{A}_1, \mathbf{A}_2) \).
and the $R^0 \times T$ matrix of factors $F = (f_1, \ldots, f_T)$. Let $\Lambda^0 = (\Lambda_1^0, \Lambda_2^0)$ be the true value of $\Lambda$. The objective function in terms of $\Lambda, F$ and $\theta$ is the sum of squared residuals (divided by $NT$)

$$
S(\Lambda, F, \theta) = (NT)^{-1} \sum_{t=1}^{T} [x_t - \mathbb{I}_{1t}(\theta) \Lambda_1 f_t - \mathbb{I}_{2t}(\theta) \Lambda_2 f_t]' [x_t - \mathbb{I}_{1t}(\theta) \Lambda_1 f_t - \mathbb{I}_{2t}(\theta) \Lambda_2 f_t].
$$

(2)

the estimators $\hat{\Lambda} = (\hat{\Lambda}_1, \hat{\Lambda}_2)$, $\hat{F} = (\hat{f}_1, \ldots, \hat{f}_T)$ and $\hat{\theta}$ for $\Lambda^0, F^0$ and $\theta^0$, respectively, with $\hat{\Lambda}_j = (\hat{\Lambda}_{j1}, \ldots, \hat{\Lambda}_{jN})'$, for $j = 1, 2$, jointly solve

$$
\hat{\Lambda}, \hat{F}, \hat{\theta} = \arg \min_{\Lambda, F, \theta} S(\Lambda, F, \theta)
.$$  

For given $\Lambda$ and $\theta$, and subject to $N^{-1}(\Lambda'_j \Lambda_j) = \mathbf{I}_{R^0}$, for $j = 1, 2$, from (2) we have

$$
\hat{f}_t(\Lambda, \theta) = N^{-1} [\mathbb{I}_{1t}(\theta) \Lambda_1 + \mathbb{I}_{2t}(\theta) \Lambda_2]' x_t, \quad t = 1, \ldots, T:
$$

(3)

replacing $f_t$ in (2) with $\hat{f}_t(\Lambda, \theta)$ obtained in (3) leads to the concentrated objective function

$$
S_F(\Lambda, \theta) = (NT)^{-1} \sum_{t=1}^{T} x_t' \{I_N - N^{-1} [\mathbb{I}_{1t}(\theta) \Lambda_1 \Lambda_1' + \mathbb{I}_{2t}(\theta) \Lambda_2 \Lambda_2']\} x_t,
$$

(4)

and the estimators for $\Lambda^0$ and $\theta^0$ jointly solve

$$
\hat{\Lambda}, \hat{\theta} = \arg \min_{\Lambda, \theta} S_F(\Lambda, \theta).
$$

From (4), the estimator for $\Lambda^0$ for given $\theta$ is defined as

$$
\hat{\Lambda}(\theta) = [\hat{\Lambda}_1(\theta), \hat{\Lambda}_2(\theta)] = \arg \max_{\Lambda} V_F(\Lambda, \theta),
$$

(5)

where

$$
V_F(\Lambda, \theta) = (NT)^{-1} \sum_{t=1}^{T} \{x_t' [\mathbb{I}_{1t}(\theta) \Lambda_1 \Lambda_1'] + \mathbb{I}_{2t}(\theta) \Lambda_2 \Lambda_2'] x_t\}
$$

$$
= (NT)^{-1} \left\{ \text{tr} \left\{ \Lambda_1 \left[ \sum_{t=1}^{T} \mathbb{I}_{1t}(\theta) x_t x_t' \right] \Lambda_1' \right\} + \text{tr} \left\{ \Lambda_2' \left[ \sum_{t=1}^{T} \mathbb{I}_{2t}(\theta) x_t x_t' \right] \Lambda_2 \right\} \right\}.
$$
The problem
\[
\max_{\Lambda} V_{\mathbf{P}}(\Lambda, \theta)
\]
is equivalent to
\[
\max_{\Lambda} \left[ \Lambda_1^T \hat{\Sigma}_{1x}(\theta) \Lambda_1 + \Lambda_2^T \hat{\Sigma}_{2x}(\theta) \Lambda_2 \right],
\]
where
\[
\hat{\Sigma}_{jx}(\theta) = \left[ (NT)^{-1} \sum_{t=1}^{T} \mathbb{1}_{jt}(\theta) \mathbf{x}_t \mathbf{x}_t' \right], \quad j = 1, 2:
\]
for \( j = 1, 2 \), and for given \( \theta \), the estimator for \( \Lambda_j^0 \) solving the problem in (6) is \( \hat{\Lambda}_j(\theta) \), where \( \hat{\Lambda}_j(\theta) \) is equal to \( \sqrt{N} \) times the \( N \times R_0^j \) matrix of eigenvectors of \( \hat{\Sigma}_{jx}(\theta) \) corresponding to its largest \( R_0^j \) eigenvalues. Replacing \( \Lambda_1 \) and \( \Lambda_2 \) in (4) with \( \hat{\Lambda}_1(\theta) \) and \( \hat{\Lambda}_2(\theta) \) leads to the concentrated sum of squared residuals (divided by \( NT \))
\[
S_{\mathbf{FA}}(\theta) = (NT)^{-1} \sum_{t=1}^{T} \mathbf{x}_t' \left\{ \mathbf{I}_N - N^{-1} \left[ \mathbb{1}_{1t}(\theta) \hat{\Lambda}_1(\theta) \hat{\Lambda}_1(\theta)' + \mathbb{1}_{2t}(\theta) \hat{\Lambda}_2(\theta) \hat{\Lambda}_2(\theta)' \right] \right\} \mathbf{x}_t:
\]
the estimator for \( \theta^0 \) then solves
\[
\hat{\theta} = \arg \min_{\theta} S_{\mathbf{FA}}(\theta).
\]
Given \( \hat{\theta} \), the estimator for \( \Lambda_j^0 \) is \( \hat{\Lambda}_j = \hat{\Lambda}_j(\hat{\theta}) \), for \( j = 1, 2 \). Finally, given \( \hat{\theta} \) and \( \hat{\Lambda} = (\hat{\Lambda}_1, \hat{\Lambda}_2) \), from (3)
\[
\hat{\mathbf{f}}_t = \hat{\mathbf{f}}_t(\hat{\Lambda}, \hat{\theta}) = N^{-1} \left[ \mathbb{1}_{1t}(\hat{\theta}) \hat{\Lambda}_1 + \mathbb{1}_{2t}(\hat{\theta}) \hat{\Lambda}_2 \right]' \mathbf{x}_t, \quad t = 1, \ldots, T.
\]

3.4 Consistency

From Theorem 3.1, the two regimes described in (1) are separately identified under Assumption 1. Define the \( R_0^j \times T \) matrices of regime-specific factors \( \mathbf{F}_0^j(\theta) = [f_{j1}^0(\theta), \ldots, f_{jT}^0(\theta)] \), for \( j = 1, 2 \), such that \( \mathbf{F}_1^0(\theta) + \mathbf{F}_2^0(\theta) = (f_1^0, \ldots, f_T^0) = \mathbf{F}_0^0 \) for any \( \theta \), and \( \mathbf{F}_1^0(\theta^0) \mathbf{F}_2^0(\theta^0)' = \mathbf{0}_{R_0^0} \). Let \( \hat{\mathbf{H}}_{jj}(\theta) \) and \( \hat{\mathbf{H}}_{mj}(\theta) \) be the rotation matrices
\[
\hat{\mathbf{H}}_{jj}(\theta) = \frac{\mathbf{F}_j^0(\theta^0) \mathbf{F}_j^0(\theta)' \Lambda_j^0(\theta)}{T} \hat{\mathbf{V}}_j(\theta)' \mathbf{N} \hat{\mathbf{V}}_j(\theta)^{-1}, \quad j = 1, 2,
\]
\[
\hat{\mathbf{H}}_{mj}(\theta) = \frac{\mathbf{F}_m^0(\theta^0) \mathbf{F}_j^0(\theta)' \Lambda_m^0(\theta)}{T} \hat{\mathbf{V}}_j(\theta)' \mathbf{N} \hat{\mathbf{V}}_j(\theta)^{-1}, \quad j, m = 1, 2, \quad j \neq m,
\]
where \( \tilde{V}_j (\theta) \) is the \( R_0 \times R_0 \) diagonal matrix of the first \( R_0 \) largest eigenvalues of \( \tilde{\Sigma}_{jx} (\theta) \) defined in (7) in decreasing order: for \( \theta = \theta^0 \) notice that \( \tilde{H}_{jj} (\theta) \) and \( \tilde{H}_{mj} (\theta) \) reduce to

\[
\tilde{H}_{jj} (\theta^0) = \frac{F_j^0 (\theta^0) F_j^0 (\theta^0)'}{T} \frac{\Lambda_j^0 \tilde{A}_j (\theta^0)}{N} \tilde{V}_j (\theta^0)^{-1}, \quad \tilde{H}_{mj} (\theta^0) = 0_{R_0}, \quad j, m = 1, 2, \quad j \neq m,
\]

and \( \tilde{H}_{jj} (\theta^0) \) becomes a regime-specific rotation matrix analogous to the one derived in Bai and Ng (2002) for linear factor models\(^3\). The following theorem shows the bias of the principal components estimator induced by the presence of regimes when \( \theta \neq \theta^0 \).

**Theorem 3.2** There exist \( R_0 \times R_0 \) matrices \( \tilde{H}_{jj} (\theta) \) and \( \tilde{H}_{mj} (\theta) \) as defined in (9) and (10), respectively, with rank \( \tilde{H}_{jj} (\theta) = R_0 \) for all \( \theta \), and rank \( \tilde{H}_{mj} (\theta) = R_0 \) for \( \theta \neq \theta^0 \), and \( C_{NT} = \min \left\{ \sqrt{N}, \sqrt{T} \right\} \), such that

\[
C_{NT}^2 \left[ \frac{1}{N} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{ji} (\theta) - \tilde{H}_{jj} (\theta) \lambda_{ji}^0 - \tilde{H}_{mj} (\theta) \lambda_{mi}^0 \right\|^2 \right] = O_p (1), \quad \forall \theta, \quad j, m = 1, 2, \quad j \neq m.
\]

Theorem 3.2 shows that the presence of regimes adds the asymptotic bias \( \tilde{H}_{mj} (\theta) \lambda_{mi}^0 \) to the principal components estimator \( \tilde{\lambda}_{ji} (\theta) \) for the space \( \tilde{H}_{jj} (\theta) \lambda_{ji}^0 \) spanned by \( \lambda_{ji}^0 \). As in linear factor models, the rate of convergence is equal to \( C_{NT}^2 = \min \{ N, T \} \) and therefore depends on the panel structure. Taking into account (10), it follows that for \( \theta = \theta^0 \),

\[
C_{NT}^2 \left[ \frac{1}{N} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{ji} (\theta^0) - \tilde{H}_{jj} (\theta^0) \lambda_{ji}^0 \right\|^2 \right] = O_p (1), \quad j = 1, 2, \quad j \neq m.
\]

which extends the result in Theorem 1 in Bai and Ng (2002) to accommodate the presence of regimes when the threshold \( \theta^0 \) is known.

Theorem 3.2 plays a key role in proving the following theorem, which states the consistency of \( \hat{\theta} \) as an estimator for \( \theta^0 \).

**Theorem 3.3** Under Assumptions I and C1-C4, \( \hat{\theta} \xrightarrow{p} \theta^0 \) as \( N, T \to \infty \).

Theorems 3.2 and 3.3 imply a number of results analogous to those collected in Theorem 1 in Stock and Watson (2002): these are stated in Corollary 3.1 below.

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\(^3\)See Bai and Ng (2002), p. 213.
Corollary 3.1 For $j = 1, 2$, and under Assumptions I and C1-C4, as $N, T \to \infty$:

(a) $\hat{\lambda}_{ji} \left( \hat{\theta} \right) \overset{p}{\to} \tilde{\lambda}_{ji} \left( \theta^0 \right) \lambda_{ji}^0$;

(b) $\tilde{f}_t \overset{p}{\to} \begin{bmatrix} \mathbb{I}_{1t} \left( \theta^0 \right) \tilde{H}_{11} \left( \theta^0 \right)^{-1} + \mathbb{I}_{2t} \left( \theta^0 \right) \tilde{H}_{22} \left( \theta^0 \right)^{-1} \end{bmatrix} f_t^0$;

(c) $\frac{1}{N} \sum_{i=1}^{N} \left\| \hat{\lambda}_{ji} \left( \hat{\theta} \right) - \tilde{\lambda}_{ji} \left( \theta^0 \right) \lambda_{ji}^0 \right\|^2 \overset{p}{\to} 0$;

(d) $\frac{1}{T} \sum_{t=1}^{T} \left\| \tilde{f}_t - \begin{bmatrix} \mathbb{I}_{1t} \left( \theta^0 \right) \tilde{H}_{11} \left( \theta^0 \right)^{-1} + \mathbb{I}_{2t} \left( \theta^0 \right) \tilde{H}_{22} \left( \theta^0 \right)^{-1} \end{bmatrix} f_t^0 \right\|^2 \overset{p}{\to} 0$.

3.5 Convergence Rates

The following theorem states the convergence rates of the concentrated least squares estimator for the threshold $\theta^0$ and of the principal components estimator for the loadings.

Theorem 3.4 Under Assumptions I, C1-C4 and CR,

$$N^{\alpha^0} T \left( \hat{\theta} - \theta^0 \right) = O_p(1)$$

and

$$C^2_{NT} \left[ \frac{1}{N} \sum_{i=1}^{N} \left\| \hat{\lambda}_{ji} \left( \hat{\theta} \right) - \tilde{\lambda}_{ji} \left( \theta^0 \right) \lambda_{ji}^0 \right\|^2 \right] = O_p(1), \quad j = 1, 2.$$

Theorem 3.4 states the superconsistency of $\hat{\theta}$ as an estimator for $\theta^0$: it extends to an infinite dimensional system the result in Chan (1993) seminal contribution. The convergence rate $N^{\alpha^0} T$ of $\hat{\theta}$ depends on the time series dimension $T$ and the number of cross-sectional units $N^{\alpha^0}$ subject to threshold effect: the rate $N^{\alpha^0} T$ monotonically increases in $\alpha^0$; since $0.5 < \alpha^0 \leq 1$ by Assumption I, then $\sqrt{NT} < N^{\alpha^0} T \leq NT$; $N^{\alpha^0} T$ is unknown since $\alpha^0$ is unknown. The higher $\alpha^0$, the stronger identification of (1) from a linear factor model, and the faster the convergence rate of $\hat{\theta}$ to $\theta^0$: this shows the connection between identification and estimation. When $\alpha^0 = 1$, all cross-sectional units are subject to threshold effect and the convergence rate is $NT$. Theorem 3.4 implies that the principal components estimator for the loadings has the same convergence rate derived in Bai and Ng (2002) in the case of linear factor models: the estimator for the threshold therefore does not affect the estimator for the loadings. Corollary 3.2 below follows from Theorem 3.4.
Corollary 3.2 Under Assumptions I, C1-C4 and CR,

\[ C^2_{NT} \left[ \frac{1}{T} \sum_{t=1}^{T} \left\| \hat{\theta} - \left[ \mathbb{I}_{1t} (\theta^0) \hat{H}_{11} (\theta^0)^{-1} + \mathbb{I}_{2t} (\theta^0) \hat{H}_{22} (\theta^0)^{-1} \right] f_t^0 \right\|^2 \right] = O_p (1). \]

Corollary 3.2 shows that the convergence rate $C_{NT}$ also applies to the principal components estimator for the factors; it also shows that the rotation induced by $\hat{f}_t$ around $f_t^0$ depends upon the regime. Corollary 3.2 justifies the robust Bai and Ng (2002) information criteria proposed in Section 4.

4 Determining the Number of Factors

We now consider the case in which the true number of factors $R_0$ in (1) (i.e., the true dimension of $f_t^0$) no longer is known and has to be determined. Breitung and Eickmeier (2011) show that neglecting structural breaks in the factor loadings inflates the estimated number of factors. Given the analogy between factor models with structural instability and (1), the latter suffers from the same problem. We rely on Corollary 3.2 and suggest a simple way to robustify Bai and Ng (2002) selection criteria to account for the threshold effect.

Given (1) and for fixed number of factors $R$, the loss function in (2) generalizes to

\[ S (\Lambda^R, F^R, \theta) = (NT)^{-1} \sum_{t=1}^{T} \left[ \mathbf{x}_t - \mathbb{I}_{1t} (\theta) \Lambda^R_1 f_t^R - \mathbb{I}_{2t} (\theta) \Lambda^R_2 f_t^R \right]^\prime \left[ \mathbf{x}_t - \mathbb{I}_{1t} (\theta) \Lambda^R_1 f_t^R - \mathbb{I}_{2t} (\theta) \Lambda^R_2 f_t^R \right], \]

(12)

where $\Lambda^R = (\Lambda^R_1, \Lambda^R_2)$, $F^R = (f^R_1, \ldots, f^R_T)$, and where the superscript $R$ denotes the dependence on the number of factors. The loss function in (12) depends on $\theta$. From Theorem 3.4, it easily follows that for any a priori chosen number of factors $R = \hat{R}$ such that $\hat{R} \geq R_0$, the estimator $\hat{\theta}^R$ for $\theta^0$ is such that $N_{\text{a.}} T (\hat{\theta}^R - \theta^0) = O_p (1)$, with $\hat{\theta}^{R_0} = \hat{\theta}$ (see Lemma A.9 in Appendix A.3): in practice, $\hat{R}$ may be chosen as discussed below. Given the convergence rate in Corollary 3.2, this naturally suggests generalizing Bai and Ng (2002) criteria by first setting $\theta = \hat{\theta}^R$ in (12) to then select $\hat{R}$ factors within each mutually exclusive regime, and therefore $\hat{R} + \hat{R}$ factors in total.

Let $\hat{\Lambda}^R (\theta)$ and $\hat{F}^R (\theta)$ be the estimators for $\Lambda^R$ and $F^R$, respectively, for any $\theta$. Given the loss function in (12), and following Bai and Ng (2002), we want penalty functions $g (N, T)$ to obtain criteria
of the form

$$PC (R, R) = S \left[ \hat{A}^R \left( \hat{\theta}^R \right), \hat{F}^R \left( \hat{\theta}^R \right), \hat{\theta}^R \right] + (R + R) \cdot g (N, T),$$

which consistently estimate the number of factors $R^0$ in each regime and therefore $(R^0 + R^0)$ factors in total: the criterion $PC (R, R)$ accounts for the fact that the threshold effect leads to a factor representation with a higher dimensional factor space, namely to a representation with $(R^0 + R^0)$ factors. Given a bounded integer $R^{\text{max}} \geq R^0$, the true number of factors $R^0$ is estimated as

$$\hat{R} = \arg \min_{1 \leq R \leq R^{\text{max}}} PC (R, R):$$

given the convergence rate $C_{NT}$ in Corollary 3.2, this leads to the threshold effect robust Bai and Ng (2002) information criteria

$$IC_{p1} (R, R) = \ln S \left[ \hat{A}^R \left( \hat{\theta}^R \right), \hat{F}^R \left( \hat{\theta}^R \right), \hat{\theta}^R \right] + (R + R) \left( \frac{N + T}{NT} \right) \ln \left( \frac{NT}{N + T} \right),$$

$$IC_{p2} (R, R) = \ln S \left[ \hat{A}^R \left( \hat{\theta}^R \right), \hat{F}^R \left( \hat{\theta}^R \right), \hat{\theta}^R \right] + (R + R) \left( \frac{N + T}{NT} \right) \ln \left( \frac{NT}{C_{NT}^2} \right),$$

$$IC_{p3} (R, R) = \ln S \left[ \hat{A}^R \left( \hat{\theta}^R \right), \hat{F}^R \left( \hat{\theta}^R \right), \hat{\theta}^R \right] + (R + R) \left[ \frac{\ln \left( \frac{C_{NT}^2}{C_{NT}^2} \right)}{C_{NT}^2} \right].$$

In practice, to obtain the estimator $\hat{\theta}^R$ for $\theta^0$, we may set $\hat{R} = R^{\text{max}}$. The following theorem states the validity of the proposed information criteria.

**Theorem 4.1** Under Assumptions I, C1-C4 and CR, the criteria $IC_{p1} (R, R)$, $IC_{p2} (R, R)$ and $IC_{p3} (R, R)$ defined in (13) consistently estimate the number of factors $R^0$.

The information criteria in (13) may be generalized by introducing a tuning multiplicative constant in the penalty as proposed in Alessi et al. (2010), who followed an idea put forward in Hallin and Liška (2007): it is high in our agenda to investigate the likely potential benefits of this method.
5 Testing for Linearity

5.1 Strategy and Test Statistic

Under Assumption I the model in (1) is identified from a linear factor model. We now extend Hansen (1996) seminal contribution to formally assess the validity of Assumption I.

Assumption LT1 - Linear Factor Model. \( \sum_{i=N^{0.5}+1}^N \delta_i = O(1) \).

Under Assumption LT1, no more than \( O(N^{0.5}) \) series undergo a regime shift. From Theorem 3.1, Assumption LT1 is the null hypothesis of linearity; Assumption I is the alternative. There exist several tests to detect structural breaks in large dimensional factor models: see Breitung and Eickmeier (2011), Han and Inoue (2015), and Yamamoto and Tanaka (2015). We follow Chen et al. (2014). Regime shifts in the loadings induce a change in the covariance matrix of the estimated factors. Let \( \tilde{\mathbf{f}} \) be the estimated number of factors in the linear model \( \mathbf{x}_t = \mathbf{A}_t \mathbf{f}_t + \mathbf{e}_t \); under Assumption LT1, \( \tilde{\mathbf{f}} \) is equal to the true number of factors, namely \( \tilde{\mathbf{f}} = R^{0} \); under Assumption I, \( \tilde{\mathbf{f}} = (R^{0} + R^{0}) \) due to neglected regime shifts.

If \( \tilde{\mathbf{f}} = 1 \) a regime shift in the loadings is ruled out with probability one. If \( \tilde{\mathbf{f}} > 1 \) we proceed as follows. Let \( \tilde{\mathbf{f}}_t \) be the \( \tilde{\mathbf{f}} \times 1 \) vector of estimated factors from \( \mathbf{x}_t = \mathbf{A}_t \mathbf{f}_t + \mathbf{e}_t \), for \( t = 1, \ldots, T \); consistently with Section 4, \( \tilde{\mathbf{f}} \) may be obtained as in Bai and Ng (2002). Following Chen et al. (2014), we construct the auxiliary threshold regression

\[
\tilde{f}_{1t} = I_{1t}(\theta) \beta_1^0 \tilde{f}_{-1,t} + I_{2t}(\theta) \beta_2^0 \tilde{f}_{-1,t} + u_t, \quad t = 1, \ldots, T, \tag{14}
\]

where \( \tilde{f}_{1t} \in \mathfrak{f} \) is the first element of \( \tilde{\mathbf{f}}_t \); \( \tilde{f}_{-1,t} \in \mathfrak{f}^{R-1} \) is the \( (\tilde{R} - 1) \times 1 \) vector containing the remaining elements of \( \tilde{\mathbf{f}}_t \); \( u_t \in \mathfrak{f} \) is the error term; \( \beta_1 \) and \( \beta_2 \) are \( (\tilde{R} - 1) \times 1 \) vectors of slope coefficients. We test Assumption LT1 in (1) by testing \( \beta_1^0 = \beta_2^0 \) in (14), where \( \beta_1^0 \) and \( \beta_2^0 \) are the true values of \( \beta_1 \) and \( \beta_2 \), respectively. This requires ruling out regime shifts in the covariance matrix of the factors. Let \( \pi^0 = \mathbb{E}[I_{1t}(\theta^0)] \) and recall \( \Sigma_f^0(\theta, \theta^0) \) in Assumption C1, for \( j = 1, 2 \).

Assumption LT2 - Threshold Effect in Factors. \( T^{-1} \sum_{t=1}^T f_{1t}^0 f_{1t}^0 \overset{p}{\rightarrow} \Sigma_0^f \) as \( T \rightarrow \infty \), \( \Sigma_{1t}(\theta^0, \theta^0) = \pi^0 \Sigma_0^0 \) and \( \Sigma_{2t}(\theta^0, \theta^0) = (1 - \pi^0) \Sigma_0^0 \), where \( \Sigma_0^0 \) is a positive definite matrix.

Assumption LT2 is analogous to Assumption 2 in Chen et al. (2014): if it fails to hold, the covariance matrix of the factors depends on the regimes and the test erroneously rejects the null hypothesis.
We build a Lagrange multiplier statistic (Hansen (1996)). Under Assumption LT1 the auxiliary regression in (14) reduces to \( \tilde{f}_{1t} = \beta_1 \tilde{f}_{-1,t} + u_t \). The estimated factors are orthogonal to each other and \( \tilde{f}_{1t} = u_t \): under the null hypothesis, the idiosyncratic component in (14) is generally serially correlated. Define \( \tilde{\mathbf{f}}_{-t} (\theta) = \begin{bmatrix} \mathbb{I}_{1t} (\theta) \tilde{f}_{-1,t}, \mathbb{I}_{2t} (\theta) \tilde{f}_{-1,t} \end{bmatrix}' \). For given \( \theta \), consider the estimator for \( \theta^0 = (\beta_1^0, \beta_2^0)' \)

\[
\hat{\beta} (\theta) = \left[ \hat{\beta}_1 (\theta)', \hat{\beta}_2 (\theta)' \right]' = \left[ \sum_{t=1}^{T} \tilde{\mathbf{f}}_{-t} (\theta) \tilde{\mathbf{f}}_{-t} (\theta)' \right]^{-1} \sum_{t=1}^{T} \tilde{\mathbf{f}}_{-t} (\theta) \tilde{f}_{1t} .
\]

For any \( (\theta_1, \theta_2) \), define the matrix \( \hat{\mathbf{M}}_{-} (\theta_1, \theta_2) = T^{-1} \sum_{t=1}^{T} \tilde{\mathbf{f}}_{-t} (\theta_1) \tilde{\mathbf{f}}_{-t} (\theta_2)' \). The regression scores \( \mathbf{k}_{-t} (\theta) = \tilde{\mathbf{f}}_{-t} (\theta) u_t \) are estimated under the null hypothesis as \( \hat{\mathbf{k}}_{-t} (\theta) = \tilde{\mathbf{f}}_{-t} (\theta) \tilde{f}_{1t} \). From Newey and West (1987), define: \( \hat{\mathbf{K}}_{-d} (\theta_1, \theta_2) = T^{-1} \sum_{t=d+1}^{T} \hat{\mathbf{k}}_{-t} (\theta_1) \hat{\mathbf{k}}_{-t-d} (\theta_2)' \), for \( d = 0, \ldots, D_T \), with \( D_T = o (T^{1/4}) \); \( \hat{\Omega}_{-} (\theta_1, \theta_2) = \hat{\mathbf{K}}_{-0} (\theta_1, \theta_2) + \sum_{d=1}^{D_T} w (d, D_T) \left[ \hat{\mathbf{K}}_{-d} (\theta_1, \theta_2) + \hat{\mathbf{K}}_{-d} (\theta_1, \theta_2)' \right] \), where \( w (d, D_T) = [1 - d/(D_T + 1)] \) is the Bartlett kernel. Define \( \mathbf{G} = (\mathbb{I}_{R-1}, -\mathbb{I}_{R-1})' \). For given \( \theta \), the heteroskedasticity and autocorrelation (HAC) robust Lagrange multiplier test statistic is

\[
\overline{LM}_{\text{HAC}}^{\theta} (\theta) = T \hat{\beta} (\theta)' \mathbf{G} \left[ \mathbf{G}' \hat{\mathbf{M}}_{-} (\theta, \theta)^{-1} \hat{\Omega}_{-} (\theta, \theta) \hat{\mathbf{M}}_{-} (\theta, \theta)^{-1} \mathbf{G} \right]^{-1} \mathbf{G}' \hat{\beta} (\theta) .
\]

For known \( \theta^0 \) and under the null hypothesis, \( \overline{LM}_{\text{HAC}}^{\theta} (\theta^0) \) has a \( \chi^2 \) limiting distribution with \( (R^0 - 1) \) degrees of freedom as \( N, T \to \infty \). However, \( \theta^0 \) is generally unknown and not identified under the null hypothesis. Following Davies (1977, 1987), and as in Hansen (1996), we propose the statistic

\[
\sup_{\theta} \overline{LM}_{\text{HAC}} = \sup_{\theta} \overline{LM}_{\text{HAC}}^{\theta} (\theta) .
\]

(15)

When factors are serially uncorrelated, it is easy to show that (15) can be simplified to

\[
\sup \overline{LM}_{\text{HC}} = \sup_{\theta} \overline{LM}_{\text{HC}}^{\theta} (\theta) ,
\]

(16)

with

\[
\overline{LM}_{\text{HC}}^{\theta} (\theta) = T \hat{\beta} (\theta)' \mathbf{G} \left[ \mathbf{G}' \hat{\mathbf{M}}_{-} (\theta, \theta)^{-1} \hat{\mathbf{K}}_{-0} (\theta, \theta) \hat{\mathbf{M}}_{-} (\theta, \theta)^{-1} \mathbf{G} \right]^{-1} \mathbf{G}' \hat{\beta} (\theta) .
\]

The heteroskedasticity robust statistic \( \sup \overline{LM}_{\text{HC}} \) in (16) is analogous to the one studied in Hansen (1996): we construct the more general heteroskedasticity and autocorrelation robust statistic in (15).
5.2 Limiting Distribution under the Null Hypothesis

Let \( \tilde{k}_{-}(\theta) = T^{-1/2} \sum_{t=1}^{T} \tilde{k}_{-t}(\theta) \) and \( k^0(\theta) \) be a zero mean Gaussian process with covariance kernel \( \Omega^0(\theta_1, \theta_2) = E [k^0(\theta_1) k^0(\theta_2)^\prime] \). Define \( \tilde{M}(\theta_1, \theta_2) = T^{-1} \sum_{t=1}^{T} [I_{1t}(\theta_1) f_{t0}^0, I_{2t}(\theta_1) f_{t0}^0] \) \( [I_{1t}(\theta_2) f_{t0}^0, I_{2t}(\theta_2) f_{t0}^0] \) and \( M^0(\theta_1, \theta_2) = E \{ [I_{1t}(\theta_1) f_{t0}^0, I_{2t}(\theta_1) f_{t0}^0] \} \) under Assumption LT5(a) below.

**Assumption LT3 - Eigenvalues.** The eigenvalues of the \( R^0 \times R^0 \) matrix \( (\Sigma_t^0 \cdot \mathbf{D}_{A_1}^0) \) are distinct.

**Assumption LT4 - Convergence Rates.** \( \sqrt{T}/N \to 0 \) as \( N \to \infty \) and \( T \to \infty \).

**Assumption LT5 - Mixing Condition and Moment Bound.**

- (a) \( \{f_t^0, z_t\}_{t=1}^{T} \) is strictly stationary and \( \beta \)-mixing, with \( \beta \)-mixing coefficients satisfying \( \beta_m = O(m^{-r}) \) for some \( \nu > \xi/(\xi - 1) \) and \( r \geq \xi > 1 \);

- (b) \( E \{ \max_{j=1,2} [\sup_{\theta} \|I_{jt}(\theta) f_{j0}^0\|^{4r}] \} < \infty \).

**Assumption LT6 - Bracketing.** For all \( \theta \), and for some \( M < \infty \) and \( \gamma > 0 \), there exists some \( \tilde{\theta} \) such that

\[
E \left[ \max_{j=1,2} \left\| I_{jt}(\theta) - I_{jt}(\tilde{\theta}) \right\| f_{j0}^0 f_{j0}^{0\prime} \right\|_{\mathbb{R}^2}^{2} \right]^{1/(2\xi)} \leq M |\theta - \tilde{\theta}|^{\gamma}.
\]

**Assumption LT7 - Uniform Convergence.** \( \tilde{M}(\theta_1, \theta_2) \) and \( \tilde{\Omega}_{-}(\theta_1, \theta_2) \) converge in probability to \( M^0(\theta_1, \theta_2) \) and \( \Omega^0_{-}(\theta_1, \theta_2) \), respectively, uniformly over \( (\theta_1, \theta_2) \), where \( M^0(\theta_1, \theta_2) \) and \( \Omega^0_{-}(\theta_1, \theta_2) \) are positive definite matrices.

Assumption LT3 is analogous to Assumption G in Bai (2003) and guarantees a unique probability limit for \( \left( A_1^0, \tilde{A}_1 / N \right) \). Assumption LT4 imposes a standard restriction on the convergence rates. Assumptions LT5-LT7 are equivalent to Assumptions 1-3 in Hansen (1996), respectively. The uniform convergence of \( \tilde{\Omega}_{-}(\theta_1, \theta_2) \) to \( \Omega^0_{-}(\theta_1, \theta_2) \) is not stringent: factors are consistently estimated under Assumptions C1-C4, LT1 and LT3; and \( \tilde{\Omega}_{-}(\theta_1, \theta_2) \) is a HAC estimator for the covariance kernel \( \Omega^0_{-}(\theta_1, \theta_2) \) (see also Assumption 11 in Chen et al. (2014)). Assumptions LT5 and LT7 jointly imply Assumption C1.

Let \( M^0(\theta_1, \theta_2) \) be such that \( \tilde{M}_{-}(\theta_1, \theta_2) \sim M^0(\theta_1, \theta_2) \) for any \( (\theta_1, \theta_2) \) as \( N, T \to \infty \): the existence of \( M^0_{-}(\theta_1, \theta_2) \) is guaranteed by Assumption LT7. Define

\[
LM_{HAC,0}^{0}(\theta) = \left[ M^0(\theta, \theta)^{-1} k^0(\theta) \right] \mathbf{G} \left[ \mathbf{G}' M^0(\theta, \theta)^{-1} \Omega^0_{-}(\theta, \theta) M^0(\theta, \theta)^{-1} \mathbf{G} \right]^{-1} \mathbf{G}' \left[ M^0(\theta, \theta)^{-1} k^0(\theta) \right]
\]
and
\[ \sup LM_{HAC,0} = \sup \theta LM_{HAC,0}^{(\theta)}. \]

**Theorem 5.1** Under Assumptions C2-C4 and LT1-LT7, \( \hat{k} (\theta) \Rightarrow k_{HAC}^{0} (\theta), \) \( \hat{LM}_{HAC} \Rightarrow LM_{HAC,0}^{0} (\theta), \) and \( \sup \hat{LM}_{HAC} \Rightarrow \sup LM_{HAC,0}, \) as \( N, T \to \infty. \)

Theorem 5.1 implies that Hansen (1996) fixed regressor bootstrap approximates the asymptotic distribution of \( \sup d_{HAC} \) in (15) under the null hypothesis \(^4\). For \( b = 1, \ldots, \tilde{b} \); (i) generate \( u_{bt} \sim \text{IID} \mathcal{N}(0, 1); \) (ii) define \( \hat{k}_{*,b} (\theta) = T^{-1/2} \sum_{t=1}^{T} \tilde{f}_{\theta} (\theta) \tilde{f}_{bt} u_{bt}^{*}; \) (iii) let \( \hat{LM}_{HAC,*}^{b} = \sup \theta \hat{LM}_{b}^{HAC,*} (\theta), \)

\[ \hat{LM}_{HAC,*}^{b} (\theta) = \left[ \hat{M}_{\theta}^{-1} \hat{k}_{*,b} (\theta) \right] \mathbf{G} \left[ \mathbf{G}' \hat{M}_{\theta}^{-1} \hat{M}_{\theta} \mathbf{G}' \right]^{-1} \mathbf{G}' \left[ \hat{M}_{\theta}^{-1} \hat{k}_{*,b} (\theta) \right]. \]

The empirical distribution of \( \left\{ \sup \hat{LM}_{b}^{HAC,*} \right\}_{b=1}^{\tilde{b}} \) approximates the asymptotic distribution of \( \sup \hat{LM}_{HAC} \) under the null hypothesis of linearity as stated in Assumption LT1.

## 6 Monte Carlo Analysis

The experiments related to estimation, model selection and linearity testing are described in Sections 6.1, 6.2 and 6.3, respectively; the results are discussed in Section 6.4.

### 6.1 Estimation

In line with the results in Section 3, we assume a known number of factors. As in Breitung and Eickmeier (2011), we analyze a one-factor model. We simulate the data using the Data Generating Process (DGP)

\[ x_{it}^{s} = \mathbb{I} (z_{it}^{s} \leq \theta^{0}) \lambda_{1i}^{0} f_{i}^{0s} + \mathbb{I} (z_{it}^{s} > \theta^{0}) \lambda_{2i}^{0} f_{i}^{0s} + e_{it}^{s}, \quad i = 1, \ldots, N, \quad t = 1, \ldots, T, \]

where \( s = 1, \ldots, S \) refers to the replication and \( S \) is the total number of replications. We set \( S = 2000, N = 25, 50, 100 \) and \( T = 100, 200, 400. \) We define \( \delta_{i}^{0} = \lambda_{2i}^{0} - \lambda_{1i}^{0}; \) we set \( \delta_{i}^{0} > 0 \) for \( i = 1, \ldots, \left[ N^{0} \right] \) and \( \delta_{i}^{0} = 0 \) for \( i = \left[ N^{0} \right] + 1, \ldots, N, \) where \( [\cdot] \) denotes the integer part of the argument. We fix the factor loadings \( \lambda_{1i}^{0} \) and \( \lambda_{2i}^{0} \) and the threshold parameter \( \theta^{0} \) throughout the replications, with \( \lambda_{1i}^{0} \sim \mathcal{N}(1, 1) \) for \( i = 1, \ldots, N \) as in the Monte Carlo experiment in Breitung and Eickmeier (2011), and \( \theta^{0} = 2. \) We control

\(^4\)A formal proof would follow similar steps as that of Theorem 2 in Hansen (1996) and it is omitted.
for: (i) the number of cross-sectional units \( N^0 \) subject to a regime change by setting \( \alpha^0 = 0.60, 1.00; \) and (ii) the magnitude of the threshold effect by setting \( \delta^0 = 0.25, 1.00, 1.75. \) We generate \( z^*_t \) as

\[
z^*_t = \mu_2 (1 - \rho_2) + \rho_2 z^*_{t-1} + (1 - \rho_2^2)^{1/2} \epsilon^*_{2t}, \quad z^*_{-50} = \mu_2, \quad t = -49, \ldots, 0, \ldots, T, \tag{17}
\]

where \( \mu_2 \) and \( \rho_2 \sim \mathcal{U}(0.05, 0.95) \) are fixed in repeated samples, and \( \epsilon^*_{2t} \sim \text{IID} \mathcal{N}(0, 1) \): in this way \( \text{E}(z^*_t) = \mu_2 \) and \( \text{Var}(z^*_t) = 1. \) We let \( \pi^0 = \text{P}(z^*_t \leq \theta^0) = \text{P}(z^*_t - \mu_2 \leq \theta^0 - \mu_2) = \Phi(\theta^0 - \mu_2) = 0.50 \) and obtain \( \mu_2 = \theta^0 - \Phi^{-1}(\pi^0) = 2: \) the choice \( \pi^0 = 0.50 \) is consistent with the existing literature (see Breitung and Eickmeier (2011), Chen et al. (2014), and Han and Inoue (2015)).

We generate the factor \( f^0_{it} \) as

\[
f^0_{it} = \rho_f f^0_{it-1} + (1 - \rho_f^2)^{1/2} \omega^*_f \epsilon^*_f, \quad f^0_{it-50} = 0, \quad t = -49, \ldots, 0, \ldots, T, \tag{18}
\]

with \( \rho_f \sim \mathcal{U}(0.05, 0.95) \) fixed in repeated samples, \( \text{E}(\omega^*_f)^2 = 1 \) and \( \epsilon^*_f \sim \text{IID} \mathcal{N}(0, 1) \), so \( \text{E}(f^0_{it}) = 0 \) and \( \text{Var}(f^0_{it}) = 1. \) We allow for conditional heteroskedasticity in \( f^0_{it} \) through the GARCH(1, 1) process

\[
(\omega^*_f)^2 = \beta_{f1} + \beta_{f2} (\omega^*_{f,t-1})^2 + \beta_{f3} (\omega^*_{f,t-1} \epsilon^*_{f,t-1})^2, \quad \text{with} \quad (\omega^*_{f,t-50})^2 = \text{E}((\omega^*_f)^2) = 1.
\]

We generate the idiosyncratic components \( e^*_it \) as

\[
e^*_it = \rho_e e^*_i,t-1 + \sigma^*_{ii} (1 - \rho_e^2)^{1/2} \omega^*_{e,t} \epsilon^*_{e,t}, \quad e^*_i,-50 = 0, \quad i = 1, \ldots, N, \quad t = -49, \ldots, 0, \ldots, T, \tag{19}
\]

with \( \rho_e \sim \mathcal{U}(0.05, 0.95) \) and \( \sigma_{ii} \sim \chi(1) \) fixed in repeated samples. Let \( e^*_{it} = (e^*_{1it}, \ldots, e^*_{N_it})' \). We allow for cross-sectional dependence through the first order spatial autoregressive process \( e^*_{it} = \tilde{Q} \Theta^*_{it} \), where

\[
\tilde{Q} = Q \left[ N / \text{tr} \left( \Sigma_{e,\text{diag}}^{1/2} \Omega_{e,\text{diag}}^{1/2} \Omega_{Q}^{1/2} \Omega_{e,\text{diag}}^{1/2} \Sigma_{e,\text{diag}}^{1/2} \right)^{1/2} \right], \quad \Sigma_{e,\text{diag}}^{1/2} = \text{diag} \left( \sigma_{11}^{1/2}, \ldots, \sigma_{NN}^{1/2} \right), \quad \Omega_{Q}^{1/2} = \text{diag} \left\{ \left[ \text{E}((\omega^*_{e,it})^2)^{1/2}, \ldots, \text{E}((\omega^*_{e,it})^2)^{1/2} \right] \right\}, \quad \Theta^*_{it} \sim \text{IID} \mathcal{N}(0, I_N) \text{, and } Q = (I_N - \iota W)^{-1} \text{ with } W =
\]

\[
\left[
\begin{array}{cccc}
0 & 1 & 0 & \ldots & 0 \\
0.5 & 0 & 0.5 & \ldots & 0 \\
0 & \ddots & \ddots & \ddots & \vdots \\
& \ddots & \ddots & \ddots & 0.5 \\
0 & \ldots & \ldots & 1 & 0
\end{array}
\right]
\]
in this way \( \text{Var} (e_{it}^s) = \sigma^2 \text{E}(\varpi_{e, t}^s)^2 / \left[ N^{-1} \sum_{i=1}^{N} \sigma^2 \text{E}(\varpi_{e, t}^s)^2 \right] \) and \( N^{-1} \sum_{i=1}^{N} \text{Var} (e_{it}^s) = 1 \). We model \( \varpi_{e, t}^s \) as the GARCH(1, 1) process \( (\varpi_{e, t}^s)^2 = \beta_{e1} + \beta_{e2} (\varpi_{e, t-1}^s)^2 + \beta_{e3} (\varpi_{e, t-1}^s e_{t-1}^s)^2 \), with \( (\varpi_{e, t-50}^s)^2 = \text{E}(\varpi_{e, t}^s)^2 = 1 \): it follows that \( \text{Var} (e_{it}^s) \to \sigma^2 \) as \( N \to \infty \).

We consider three scenarios: (i) time homoskedastic factors and idiosyncratic components, and cross-sectionally independent idiosyncratic components (CSI); (ii) time homoskedastic factors and idiosyncratic components, and cross-sectionally dependent idiosyncratic components (CSD); and (iii) time heteroskedastic factors and idiosyncratic components, and cross-sectionally dependent idiosyncratic components (CSDH). Under CSI, we set \( \beta_{f1} = \beta_{e1} = 0, \beta_{f2} = \beta_{e2} = 0, \beta_{f3} = \beta_{e3} = 0 \) and \( \iota = 0 \). We build CSD by imposing \( \beta_{f1} = \beta_{e1} = 1, \beta_{f2} = \beta_{e2} = 0, \beta_{f3} = \beta_{e3} = 0 \) and \( \iota = 0.4 \). We parameterize CSDH by setting \( \beta_{f1} = \beta_{e1} = 0.1, \beta_{f2} = \beta_{e2} = 0.8, \beta_{f3} = \beta_{e3} = 0.1 \) and \( \iota = 0.4 \).

To reduce the effect induced by the initial values \( z_{-50}^s = \mu_z, f_{-50}^0 = 0, \varpi_{e, -50}^s = 1, e_{i, -50}^s = 0 \) and \( \varpi_{e, t}^s = 1 \), we discard the first 50 observations in the DGPs for \( z_t^s, f_t^0, \varpi_t^s, e_t^s, \) and \( \varpi_t^s \). We estimate factor and loadings as detailed in Section 3.3. Given the convergence rates Theorem 3.4, the estimator for \( \theta^0 \) is asymptotically independent of that for \( \lambda_{11}^0, \lambda_{22}^0 \) and \( f_{11}^0 \). As in Tong and Lim (1980), Tsay (1989) and Kapetanios (2000), we estimate \( \theta^0 \) by grid search: we implement the algorithm by selecting 19 equally spaced quantiles of the empirical distribution function of \( z_t^s \), namely \{5%, 10%, 15%, ..., 85%, 90%, 95%\}, and the true value \( \theta^0 = 2 \). Given the concentrated least squares estimator \( \hat{\theta}^s \) for \( \theta^0 \), we estimate factor and loadings by principal components. We assess \( \hat{\theta}^s \) by computing

\[
\text{bias} = S^{-1} \sum_{s=1}^{S} \left( \hat{\theta}^s - \theta^0 \right), \quad \text{RMSE} = \sqrt{S^{-1} \sum_{s=1}^{S} (\hat{\theta}^s - \theta^0)^2}.
\]

Finally, given the estimator \( \hat{e}_{it}^s = \mathbb{I} (z_t^s \leq \hat{\theta}^s) \lambda_{11}^s f_{11}^s + \mathbb{I} (z_t^s > \hat{\theta}^s) \lambda_{22}^s f_{22}^s \) for the common component

\[
e_{it}^0 = \mathbb{I} (z_t^s \leq \theta^0) \lambda_{11}^0 f_{11}^0 + \mathbb{I} (z_t^s > \theta^0) \lambda_{22}^0 f_{22}^0 \],
\]

we report

\[
\text{MSE} = S^{-1} \sum_{s=1}^{S} (NT)^{-1} \sum_{i=1}^{N} \sum_{t=1}^{T} (\hat{e}_{it}^s - e_{it}^0)^2.
\]
6.2 Model Selection

We simulate the data using the two-factor DGP

\[ x_{it}^s = \mathbb{I}\left(z_t^s \leq \theta^0\right) (\lambda_{11i} f_{1t}^{0s} + \lambda_{12i} f_{2t}^{0s}) + \mathbb{I}\left(z_t^s > \theta^0\right) (\lambda_{21i} f_{1t}^{0s} + \lambda_{22i} f_{2t}^{0s}) + e_{it}^s, \quad i = 1, \ldots, N, \quad t = 1, \ldots, T, \]

with \( \lambda_{11i} \sim \mathcal{N}(1, 1) \), \( \lambda_{12i} \sim \mathcal{N}(1, 1) \), \( \lambda_{21i} = \lambda_{11i} + \delta_i^0 \) and \( \lambda_{22i} = \lambda_{12i} + \delta_i^0 \). We set \( \delta_i^0 = 0.25, 1.00, 1.75 \) for \( i = 1, \ldots, [N^{\alpha_0}] \), and \( \delta_i^0 = 0 \) for \( i = [N^{\alpha_0}] + 1, \ldots, N \), with \( \alpha_0 = 0.60 \). The factors \( f_{1t}^{0s} \) and \( f_{2t}^{0s} \) are generated as AR(1) processes analogous to (18); \( z_t^s \) and \( e_{it}^s \) are as in (17) and (19), respectively. The model has \( R^0 = 2 \) factors and it is estimated with \( R_{\text{max}} = 8 \). We assess the model selection criteria in (13) by reporting the average number of estimated factors over the 2000 replications.

6.3 Linearity Testing

Under the null hypothesis, we simulate the data from the linear two-factor model

\[ x_{it}^s = \lambda_{1i} f_{1t}^{0s} + \lambda_{2i} f_{2t}^{0s} + e_{it}^s, \quad i = 1, \ldots, N, \quad t = 1, \ldots, T, \]

with \( \lambda_{1i} \sim \mathcal{N}(1, 1) \), \( \lambda_{2i} \sim \mathcal{N}(1, 1) \). The factors \( f_{1t}^{0s} \) and \( f_{2t}^{0s} \) are generated as AR(1) processes analogous to (18) and we look at two cases: (i) \( \rho_f = 0 \), factors are serially uncorrelated and the heteroskedasticity robust statistic in (16) is used; and (ii) \( \rho_f = 0.5 \), factors have time dependence and the HAC statistic in (15) is used with Barlett window \( D_T = 5 \). Under the alternative hypothesis, we simulate the data from the one-factor model in Section 6.1, with \( \alpha^0 = 0.60 \): we set \( \rho_f = 0.5 \) in (18), factors are serially correlated and the HAC statistic in (15) is used. We set the number of bootstrap replications to \( \bar{b} = 1000 \).

6.4 Results

The results are collected in four tables: Tables 1 and 2 focus on estimation; model selection criteria are assessed in Table 3; size and power of the linearity test are shown in Table 4.

Table 1 about here

Table 2 about here
Table 3 about here

Table 4 about here

Table 1 displays results for the concentrated least squares estimator $\hat{\theta}$ for $\theta^0 = 2$ when $\alpha^0 = 0.60$ (Panel A) and $\alpha^0 = 1.00$ (Panel B). Given Theorems 3.1 and 3.4, a higher $\alpha^0$ leads to stronger identification of $\theta^0$ and faster convergence rate of $\hat{\theta}$ to $\theta^0$, respectively: in line with these theoretical results, the RMSE of $\hat{\theta}$ when $\alpha^0 = 1.00$ is generally lower than the homologous value when $\alpha^0 = 0.60$ under CSI, CSD and CSDH. The RMSE tends to decrease with $N$, $T$ and $\delta^0_i > 0$. The RMSE also increases as cross-sectional dependence and time heteroskedasticity are added to the DGP as compared to the CSI scenario. The bias displays a pattern somehow similar to that of the RMSE.

Table 2 shows the MSE of the common components when $\alpha^0 = 0.60$ (Panels A) and $\alpha^0 = 1.00$ (Panels B). We assess the empirical validity of Theorem 3.4 by considering both unfeasible and feasible estimators, the former and the latter being obtained by setting $\theta = \theta^0$ and $\theta = \hat{\theta}$, respectively. In line with Theorem 3.4, the MSE of the feasible estimator converges to that of the unfeasible counterpart as both $N$ and $T$ increase. The MSE monotonically decreases in $N$ and $T$, and in $\delta^0_i > 0$ for $N = 25$, whereas it does not exhibit any systematically noticeable difference between $\alpha^0 = 0.60$ and $\alpha^0 = 1.00$. The MSE also increases when cross-sectional dependence is added to the DGP, whereas it seems to be less affected by time heteroskedasticity.

Table 3 collects results for the selection criteria $IC_{p1}(R, R)$, $IC_{p2}(R, R)$ and $IC_{p3}(R, R)$ (Panels A, B and C, respectively) in (13) when $\alpha^0 = 0.60$. The criteria $IC_{p1}(R, R)$ and $IC_{p2}(R, R)$ display a similar behavior under CSI, with the latter having a hedge over the former: they tend to overestimate the number of factors for $N = 25, 50$, whereas they perform well for $N = 100$. The criterion $IC_{p2}(R, R)$ is the best under both CSD and CSDH, where the performance of $IC_{p2}(R, R)$ slightly deteriorates as compared to CSI. The criterion $IC_{p3}(R, R)$ is the least accurate under all scenarios. Finally, unfeasible and feasible estimators give similar results in terms of model selection performance.

Finally, Table 4 reports results for the linearity test at 5% and 10% level (Panels A and B, respectively). Regardless of $\rho_f$ and $N$, the test is correctly sized for $T = 400$. It is undersized for lower values of $T$, with the exception of scenario CSDH with $\rho_f = 0.00$ and $T = 200$. The test has size properties analogous to Breitung and Eickmeier (2011) Lagrange multiplier test under unknown break-point. The
power increases in $N$, $T$ and $\delta_0 > 0$, though the effect of size distortions ought to be taken into account.

In conclusion, the Monte Carlo findings corroborate the theoretical results stated in Theorems 3.1 and 3.4. They confirm the validity of the information criteria in (13) and suggest using $IC_{p2}(R, R)$. Finally, they show that the proposed linearity test is able to detect regime shifts.

7 Empirical Application

We show how our framework may be used to measure connectedness in multivariate nonlinear dynamic systems, with a focus on financial variables: a threshold factor specification is suitable when "history repeats", as in financial markets, which undergo regime shifts (Timmermann (2008), and Ang and Timmermann (2012)). Section 7.1 proposes a measure of connectedness, Section 7.2 describes the data and the empirical model, and Section 7.3 presents the results.

7.1 Measure of Connectedness

Connectedness is central to risk measurement and management. There exist several measures of connectedness, which are based on different underlying metrics: examples are the marginal expected shortfall of Acharya et al. (2010), the equicorrelation approach of Engle and Kelly (2012), the network approach of Diebold and Yilmaz (2014), and the CoVaR of Adrian and Brunnermeier (2016). In line with our methodological contribution, we focus on the principal components approach of Billio et al. (2012).

Given the sequence of $N \times 1$ vectors $\{x_t\}_{t=1}^T$, let $\{\omega_r\}_{r=1}^N$ be the sequence of eigenvalues of the $N \times N$ covariance matrix $\Sigma_x = (NT)^{-1} \sum_{t=1}^T x_t x_t'$. In relation to financial markets, Billio et al. (2012) quantify the degree of connectedness amongst the elements of $x_t$ as the risk associated to the first $R$ eigenvalues in relation to the overall risk of the system. Formally, they measure connectedness through\(^5\)

$$C(R) = \frac{\sum_{r=1}^R \omega_r}{\sum_{r=1}^N \omega_r} :$$

by construction $C(R)$ is increasing in $R$; for given $R$, a higher $C(R)$ denotes higher connectedness amongst the underlying variables. The measure $C(R)$ powerfully captures connectedness amongst random variables. However, it suffers from two main drawbacks. First, the number of eigenvalues $R$ is

\(^5\)Billio et al. (2012) refer to $C(R)$ as to the Cumulative Risk Fraction.
chosen *a priori* and not according to a selection criterion. Second, $C(R)$ refers to the entire time series dimension $T$ and is unable to detect variations in connectedness induced by a threshold effect. Financial markets experience regimes shifts (Timmermann (2008), and Ang and Timmermann (2012)): the measure $C(R)$ may not accurately describe the dynamics in connectedness of the variables of interest.\textsuperscript{6} Our methodology allows to build a connectedness measure that accommodates regime shifts and relies on the optimally selected number of eigenvalues.

Let $\{\omega_{jr}\}_{r=1}^{N}$ be the sequence of eigenvalues of the $N \times N$ covariance matrix $\Sigma_{jx}(\theta)$ defined in (7) in decreasing order, for $j = 1, 2$. We generalize $C(R)$ and measure connectedness through

$$C_j(\hat{R}) = \frac{\sum_{r=1}^{\hat{R}} \omega_{jr}}{\sum_{r=1}^{N} \omega_{jr}}, \quad j = 1, 2.$$  \textsuperscript{(20)}

Compared to $C(R)$, the measure $C_j(\hat{R})$ has two distinctive features: it quantifies connectedness within each regime; and the number of eigenvalues $\hat{R}$ is optimally determined according to the criteria in (13).

### 7.2 Data and Model Specification

We construct the vector of dependent variables from the updated monthly financial dataset employed in Jurado *et al.* (2015) and, on a quarterly frequency, in Ludvigson and Ng (2007): this consists of a panel of 147 series related to the U.S. financial markets, as detailed in Ludvigson and Ng (2007).

We study how economic policy uncertainty affects connectedness amongst financial variables. The threshold variable is the lagged index of economic policy uncertainty proposed in Baker *et al.* (2016): a higher index value denotes higher uncertainty. Financial markets uncertainty leads to economic policy uncertainty and the threshold variable is likely to be predetermined (see discussion in Section 3.1.2).

Due to data availability issues, we perform the empirical analysis over the period running from January 1985 to December 2014, a total of 360 observations. The threshold variable has mean, standard deviation, maximum and minimum equal to 107.640, 32.566, 245.127 and 57.203, respectively.

We fit a linear factor model to the data and select 8 factors using the $IC_{p2}(R)$ criterion of Bai and Ng (2002). Neither $\sup \overset{\text{HAC}}{LM}$ nor $\sup \overset{\text{HC}}{LM}$ in (15) and (16), respectively, reject the null of linearity: \textsuperscript{8}

\footnote{\textsuperscript{6}Billio et al. (2012) measure the dynamic degree of connectedness in financial returns by computing $C(R)$ over rolling windows. \textsuperscript{7}I am very grateful to Sydney Ludvigson for providing me with the updated version of the dataset I am using in the paper. See Jurado et al. (2015) for a more detailed description of the data. \textsuperscript{8}The index is made available at http://www.policyuncertainty.com/ .}
the tests are likely to have low power when applied to financial data, as market efficiency limits factors explanatory ability. As customary in empirical asset pricing, we still select two regimes (see Ang and Timmermann (2012)). We consider \( R_{\text{max}} = 10 \) and estimate the change-point by setting \( \hat{R} = R_{\text{max}} \); we then construct a grid for the change-point with lowest and highest values equal to 5% and 95%, respectively, and step equal to 0.5%. The number of factors are selected according to the criteria in (13).

7.3 Results

Results are collected in Table 5.

Table 5 about here

The point estimate for the threshold \( \theta^0 \) is \( \hat{\theta} = 131.413 \): this splits the sample into low and high economic policy uncertainty regimes, with frequencies equal to \( \hat{\pi} = 0.783 \) and \( 1 - \hat{\pi} = 0.217 \), respectively. Figure 1 shows the high uncertainty regime, as identified by \( I(z_t > \hat{\theta}) = 1 \), plotted against time.

Figure 1 about here

The criteria \( IC_{p1}(R, R) \) and \( IC_{p2}(R, R) \) select \( \hat{R} = 3 \) factors, with connectedness measures \( C_1(\hat{R}) = 0.678 \) and \( C_2(\hat{R}) = 0.865 \). Conversely, \( IC_{p3}(R, R) \) selects \( \hat{R}_1 = 6 \) factors: this is consistent with the Monte Carlo results in Section 6.4, which show that \( IC_{p3}(R, R) \) overestimates the number of factors in finite samples. Our results show that connectedness amongst financial variables increases with economic policy uncertainty: this likely to be relevant for risk measurement and management.

8 Directions for Future Research

We outline two directions for future research. It would be useful to apply to (1) the projected principal components estimator of Fan et al. (2016a). By including additional covariates in the information set, this would allow to consistently estimate factors and loadings without requiring \( T \to \infty \): this would be important as the regimes in (1) effectively reduce the available time dimension.

Following Fan et al. (2013, 2016b), and Bai and Liao (2016), it would be interesting to introduce conditional sparsity in (1). Conditional sparsity allows to estimate the error covariance matrix in large dimensional approximate factor models by imposing that many entries are zero or nearly zero. In a linear
framework, Fan et al. (2013) develop a two-step procedure that first estimates factors and loadings by principal components, and then applies a thresholding procedure to the remaining covariance matrix. Bai and Liao (2016) propose a penalized maximum likelihood method that jointly estimates loadings and error covariance matrix: the factors are then estimated by generalized least squares. Fan et al. (2016b) robustify Fan et al. (2013) estimator to account for asymmetric and heavy tailed error distribution. As applied to (1), conditional sparsity would have to be imposed within each regime: this would allow to estimate regime-specific error covariance matrices; from the superconsistency property in Theorem 3.4, the results in Fan et al. (2013, 2016b), and Bai and Liao (2016) would then apply within each regime.

9 Conclusions

We study least squares estimation of large dimensional factor models with threshold-type regime shifts in the loadings. Our methodology handles the general case of unknown threshold parameter. The concentrated least squares estimator for the threshold value is superconsistent: the convergence rate depends on the time series dimension and on the number of cross-sectional units subject to threshold effect. The principal components estimator for factors and loadings has the same convergence rate as in linear factor models: this allows to robustify Bai and Ng (2002) selection criteria by accounting for the higher dimensional factor space representation induced by the regime shift. We also propose a simple yet powerful linearity test to detect regime changes. In an application, we document an increase in connectedness amongst financial variables during periods of high economic policy uncertainty: this result is likely to be relevant for risk measurement and management.

A Proofs of Theorems

A.1 Proofs of Results in Section 3.4

We rely on the following lemmas.

Lemma A.1 Under Assumptions I and C1-C3, there exists some positive constant $M < \infty$ such that for all $\theta$, all $(N,T)$ and $j = 1,2$:

(a) $N^{-1} \sum_{i=1}^{N} \sum_{l=1}^{N} \sigma_{jl}^2(\theta) \leq M$;

(b) $E \left\{ N^{-2} \sum_{i=1}^{N} \sum_{l=1}^{N} \left[ T^{-1} \sum_{t=1}^{T} \bar{z}_{jt}(\theta) x_{it} x_{lt} \right]^2 \right\} \leq M$;
Lemma A.2 Given $\hat{H}_{jj}(\theta)$ and $\hat{H}_{mj}(\theta)$ defined in (9) and (10), respectively, for $j = 1, 2$, and $j \neq m$, and for any $\theta$,

$$S_{FA}(\theta) - S_{F} \left[ \Lambda_{1}^{0} \hat{H}_{11}(\theta) + \Lambda_{2}^{0} \hat{H}_{21}(\theta), \Lambda_{3}^{0} \hat{H}_{22}(\theta) + \Lambda_{4}^{0} \hat{H}_{12}(\theta) \right] = O_{p} \left( \frac{1}{N^{1/2}} \right).$$

Lemma A.3 There exists a $\tau(\theta) > 0$ such that

$$\liminf_{N,T \to \infty} S_{F} \left[ \Lambda_{1}^{0} \hat{H}_{11}(\theta) + \Lambda_{2}^{0} \hat{H}_{21}(\theta), \Lambda_{3}^{0} \hat{H}_{22}(\theta) + \Lambda_{4}^{0} \hat{H}_{12}(\theta) \right] - S_{F} \left( \Lambda_{1}^{0}, \Lambda_{2}^{0}, \theta^{0} \right) = \tau(\theta), \quad \forall \theta \neq \theta^{0}.$$

Proof of Theorem 3.1. As defined in Section 3.2, $\tilde{V}_{1}$ is the $R^{0} \times R^{0}$ diagonal matrix of the first $R^{0}$ largest eigenvalues of $\hat{S}_{N} = (NT)^{-1} \sum_{t=1}^{T} x_{t} x_{t}'$ in decreasing order, and $\hat{A}_{1}$ is the estimator for $A_{1}^{0}$ in the true data generating process $x_{t} = A_{1}^{0} f_{1t}^{0} + \varepsilon_{t}(\theta^{0}) A_{2}^{0} f_{2t}^{0} + \varepsilon_{t}$ from the misspecified linear model $x_{t} = A_{1} f_{t} + \varepsilon_{t}$: the equality $\hat{S}_{N} \hat{A}_{1} = \hat{A}_{1} \tilde{V}_{1}$ then holds by the definitions of eigenvectors and eigenvalues. Applying the normalization $N^{-1} \hat{A}_{1}^{'} \hat{A}_{1} = 1_{RF}$ to implement the principal components estimator, it follows that $N^{-1} \sum_{t=1}^{N} \left\| \tilde{A}_{1t} \right\|^{2} = O_{p}(1)$. By Lemma A.3 in Bai (2003), $\tilde{V}_{1} \overset{p}{\rightarrow} V_{1}$ where $V_{1}$ is a positive definite matrix: we then focus on $\left\| \tilde{V}_{1} \left( \tilde{A}_{1} - \hat{A}_{1} A_{1}^{0} \right) \right\|^{2}$. Theorem 3.1 relies on the identity

$$\tilde{V}_{1} \left( \tilde{A}_{1} - \hat{A}_{1} A_{1}^{0} \right) = N^{-1} \sum_{t=1}^{N} \hat{A}_{1t} \sigma_{1t}(\theta^{0}) + N^{-1} \sum_{t=1}^{N} \hat{A}_{1t} \sigma_{1t}(\theta^{0}) + N^{-1} \sum_{t=1}^{N} \hat{A}_{1t} \sigma_{2t}(\theta^{0}) + N^{-1} \sum_{t=1}^{N} \hat{A}_{1t} \sigma_{2t}(\theta^{0}) \tilde{e}_{tt} \tilde{e}_{tt} \tilde{e}_{tt} \tilde{e}_{tt},$$

where

$$\gamma_{jtt}(\theta) = T^{-1} \sum_{t=1}^{T} I_{jt}(\theta) e_{jt} e_{jt} - \sigma_{jtt}(\theta), \quad j = 1, 2,$$

$$\varphi_{jtt}(\theta) = T^{-1} \sum_{t=1}^{T} I_{jt}(\theta) \left[ I_{jt}(\theta^{0}) A_{1t}^{0} f_{1t}^{0} + I_{jt}(\theta^{0}) A_{2t}^{0} f_{2t}^{0} \right] e_{jt}, \quad j = 1, 2,$$

$$\varphi_{tt} = \varphi_{1tt}(\theta) + \varphi_{2tt}(\theta) = T^{-1} \sum_{t=1}^{T} \left[ I_{tt}(\theta^{0}) A_{1t}^{0} f_{1t}^{0} + I_{tt}(\theta^{0}) A_{2t}^{0} f_{2t}^{0} \right] e_{tt},$$

$$\varphi_{it} = \varphi_{1it}(\theta) + \varphi_{2it}(\theta) = T^{-1} \sum_{t=1}^{T} \left[ I_{jt}(\theta^{0}) A_{1t}^{0} f_{1t}^{0} + I_{jt}(\theta^{0}) A_{2t}^{0} f_{2t}^{0} \right] e_{jt}, \quad j = 1, 2,$$

$$\varphi_{iit} = \varphi_{1iit}(\theta) + \varphi_{2iit}(\theta) = T^{-1} \sum_{t=1}^{T} \left[ I_{jtt}^{0} f_{1t}^{0} + I_{jt}^{0} f_{2t}^{0} \right] e_{jt}, \quad j = 1, 2,$$

$$\psi_{it} = T^{-1} \sum_{t=1}^{T} I_{jt}(\theta^{0}) \delta_{t}^{0} f_{1t}^{0} \delta_{t}^{0} f_{2t}^{0}, \quad \psi_{iit} = T^{-1} \sum_{t=1}^{T} I_{jtt}(\theta^{0}) \delta_{t}^{0} f_{1t}^{0} \delta_{t}^{0} f_{2t}^{0}.$$

The matrix $\hat{H}_{1}$ depends on $N$ and $T$: this dependence is implicitly suppressed to keep notation simple. Notice that

$$\left\| \hat{H}_{1} \right\| \leq \left\| \frac{F_{0} f_{0}^{0}}{T} \right\| \left\| \frac{A_{0}^{0}}{N} \right\|^{1/2} \left\| \frac{\tilde{V}_{1} \tilde{V}_{1}^{-1}}{N} \right\|^{1/2} = O_{p}(1),$$

by Assumptions C1 and C2. By Loève’s inequality,

$$N^{-1} \sum_{t=1}^{N} \left\| \tilde{V}_{1} \left( \tilde{A}_{1t} - \hat{A}_{1t} A_{1}^{0} \right) \right\|^{2} \leq 9N^{-1} \sum_{t=1}^{N} \left\{ \tilde{\sigma}_{1t}(\theta) + \tilde{\sigma}_{1t}(\theta) + \tilde{\sigma}_{2t}(\theta) + \tilde{\sigma}_{2t}(\theta) + \tilde{\varphi}_{iit}(\theta) + \tilde{\varphi}_{iit}(\theta) + \tilde{\psi}_{iit}(\theta) + \tilde{\psi}_{iit}(\theta) \right\}.$$
where
\[
\delta_{ji} (\theta) = N^{-2} \left\| \sum_{l=1}^{N} \widetilde{\lambda}_{1l} \sigma_{jli} (\theta) \right\|^2, \quad \tilde{\delta}_{ji} (\theta) = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \sigma_{jli} (\theta) \right\|^2, \quad j = 1, 2,
\]
\[
\hat{\varphi}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right\|^2, \quad \tilde{\varphi}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right\|^2,
\]
\[
\hat{\sigma}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \sigma_{il} \right\|^2, \quad \tilde{\sigma}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \sigma_{il} \right\|^2,
\]
\[
\hat{\psi}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \psi_{il} \right\|^2.
\]

We first consider \( \hat{\delta}_{1i} (\theta) \): \( \tilde{\delta}_{2i} (\theta) \) is analogous and omitted. We have
\[
N^{-1} \sum_{i=1}^{N} \hat{\delta}_{1i} (\theta) \leq N^{-1} \left( N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right) \left[ N^{-1} \sum_{i=1}^{N} \sum_{l=1}^{N} \sigma_{il}^2 (\theta) \right] = O_p \left( N^{-1} \right)
\]
by Lemma A.1(a). As for \( \tilde{\delta}_{ji} (\theta) \), for \( j = 1 \) \((j = 2 \) is analogous),
\[
N^{-1} \sum_{i=1}^{N} \tilde{\delta}_{ji} (\theta) \leq N^{-1} \left( N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right) \left[ N^{-1} \sum_{i=1}^{N} \sum_{l=1}^{N} \sigma_{il}^2 (\theta) \right] = O_p \left( N^{-1} \right)
\]
and
\[
\sum_{i=1}^{N} \tilde{\varepsilon}_{1i} (\theta) \leq O_p (1) \sqrt{\frac{N^2}{T^2}} = O_p \left( \frac{N}{T} \right)
\]
by Assumption C3(d), then
\[
\sum_{i=1}^{N} \tilde{\varepsilon}_{1i} (\theta) = O_p (T^{-1}).
\]
Regarding \( \hat{\varphi}_i \), we have
\[
\hat{\varphi}_i = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right\|^2 = N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \left\{ T^{-1} \sum_{t=1}^{T} e_{1t} \right\} \left\{ \varepsilon_{t0} \tilde{f}_t (\theta^0) + \varepsilon_{t2} (\theta^0) \tilde{f}_t^{(2)} \right\} \right\|^2 \leq N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \left\{ T^{-1} \sum_{t=1}^{T} \varepsilon_{t0} \tilde{f}_t (\theta^0) \left\{ \tilde{f}_t^{(0)} - \tilde{f}_t^{(2)} \right\} \right\} \right\|^2 \leq N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \left\{ T^{-1} \sum_{t=1}^{T} \varepsilon_{t0} \left\{ \tilde{f}_t^{(0)} - \tilde{f}_t^{(2)} \right\} \right\} \right\|^2 \leq N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \right\|^2 \left\{ N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right\} \left\{ N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right\} \leq N^{-2} \left\| \sum_{l=1}^{N} \tilde{\lambda}_{1l} \right\|^2 \left\{ N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right\} \left\{ N^{-1} \sum_{i=1}^{N} \left\| \tilde{\lambda}_{1i} \right\|^2 \right\} = O_p (1)
\]
and
\[
N^{-1} \sum_{i=1}^{N} \tilde{\varphi}_i = \left\{ \left\{ N^{-1} \sum_{i=1}^{N} \left[ T^{-2} \left\| \sum_{l=1}^{T} \mathbf{I}_{1l} (\theta^0) \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \right\|_2^2 \right] \right\} O_p (1) \right. + \left. \left\{ N^{-1} \sum_{i=1}^{N} \left[ T^{-2} \left\| \sum_{l=1}^{T} \mathbf{I}_{2l} (\theta^0) \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \right\|_2^2 \right] \right\} O_p (1) \right) O_p (1) = O_p \left( T^{-1} \right)
\]
by Assumptions C2 and C4. In a similar way, it is proved that \( \tilde{\varphi}_i = O_p \left( T^{-1} \right) \). As for \( \tilde{\varphi}_i \),
\[
\tilde{\varphi}_i = N^{-2} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right\}^2 = N^{-2} \left( \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right)^T \left( \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \right) = N^{-1} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \left[ T^{-1} \sum_{l=1}^{T} \mathbf{I}_{1l} (\theta^0) \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \delta_l^0 \right] \right\}^T N^{-1} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \varphi_{il} \left[ T^{-1} \sum_{l=1}^{T} \mathbf{I}_{1l} (\theta^0) \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \delta_l^0 \right] \right\} = N^{-1} O_p \left( N^{0 \alpha} \right) \cdot N^{-1} O_p \left( N^{0 \alpha} \right) = O_p \left( N^{2 \alpha \alpha - 2} \right).
\]
In a similar way, it can be proved that \( \tilde{\varphi}_i = O_p \left( N^{2 \alpha \alpha - 2} \right) \). Finally, under Assumptions C1 and C2,
\[
\tilde{\psi}_i = N^{-2} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \psi_{il} \right\}^2 = N^{-2} \left( \sum_{l=1}^{N} \tilde{\lambda}_{1l} \psi_{il} \right)^T \left( \sum_{l=1}^{N} \tilde{\lambda}_{1l} \psi_{il} \right) = N^{-1} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \left[ T^{-1} \sum_{l=1}^{T} \mathbf{I}_{1l} (\theta^0) \delta_l^0 \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \delta_l^0 \right] \right\}^T N^{-1} \left\{ \sum_{l=1}^{N} \tilde{\lambda}_{1l} \left[ T^{-1} \sum_{l=1}^{T} \mathbf{I}_{1l} (\theta^0) \delta_l^0 \mathbf{f}_l^{\theta_0} \mathbf{e}_{nl} \delta_l^0 \right] \right\} = N^{-1} O_p \left( N^{0 \alpha} \right) N^{-1} O_p \left( N^{0 \alpha} \right) = O_p \left( N^{2 \alpha \alpha - 2} \right).
\]
Combining all above results, we have
\[
N^{-1} \sum_{i=1}^{N} \left\| \mathbf{V}_1 \left( \mathbf{\tilde{A}}_{1i} - \mathbf{\tilde{A}}_{1i} \mathbf{\lambda}_{1i}^0 \right) \right\|^2 = O_p \left( N^{-1} \right) + O_p \left( T^{-1} \right) + O_p \left( N^{2 \alpha \alpha - 2} \right),
\]
which completes the proof of the theorem. \( \blacksquare \)

**Proof of Theorem 3.2.** From Theorem 3.1, by Assumption I the regime indicator \( \mathbf{I}_{1j} (\theta) \) is identified, for \( j = 1, 2 \): we can then split the sample according to the value of \( \mathbf{I}_{1j} (\theta) \). We consider the case \( j = 1 \): the case \( j = 2 \) is analogous and omitted. As defined in Section 3.4, \( \mathbf{V}_1 (\theta) \) is the \( R^0 \times R^0 \) diagonal matrix of the first \( R^0 \) largest eigenvalues of \( \mathbf{\tilde{S}}_{1x} (\theta) \) in (7) in decreasing order: the equality \( \mathbf{\tilde{S}}_{1x} (\theta) \mathbf{\tilde{A}}_1 (\theta) = \mathbf{\tilde{A}}_1 (\theta) \mathbf{\tilde{V}}_1 (\theta) \) holds by the definitions of eigenvectors and eigenvalues.

From the normalization \( -N^{-1} \mathbf{\tilde{A}}_1 (\theta)' \mathbf{\tilde{A}}_1 (\theta) = \mathbf{I}_{R^0} \), it follows that \( N^{-1} \sum_{i=1}^{N} \left\| \mathbf{\tilde{A}}_1 (\theta) \right\|^2 = O_p (1) \) for all \( \theta \). By Lemma A.3 in Bai (2003), \( \mathbf{\tilde{V}}_1 (\theta) \overset{p}{=} \mathbf{V}_1 (\theta) \) where \( \mathbf{V}_1 (\theta) \) is a positive definite matrix for all \( \theta \), and \( \left\| \mathbf{\tilde{V}}_1 (\theta) \right\| = O_p (1) \): we then focus
on $\| V_1 (\theta) \left[ \hat{\lambda}_{ii} (\theta) - \hat{H}_{11} (\theta)' \lambda_{i1}^0 - \hat{H}_{21} (\theta)' \lambda_{i2}^0 \right] \|^2$. Theorem 3.2 relies on the identity

$$
V_1 (\theta) \left[ \hat{\lambda}_{ii} (\theta) - \hat{H}_{11} (\theta)' \lambda_{i1}^0 - \hat{H}_{21} (\theta)' \lambda_{i2}^0 \right] = N^{-1} \sum_{t=1}^N \hat{\lambda}_{tt} (\theta) \sigma_{1tt} (\theta) + N^{-1} \sum_{t=1}^N \hat{\lambda}_{tt} (\theta) \varphi_{1tt} (\theta)
$$

where $\sigma_{1tt} (\theta)$, $\varphi_{1tt} (\theta)$ and $\varphi_{2tt} (\theta)$ are defined in (21). The matrices $\hat{H}_{11} (\theta)$ and $\hat{H}_{21} (\theta)$ both depend on $N$ and $T$: this dependence is implicitly suppressed to keep notation simple. Notice that

$$
\left\| \hat{H}_{11} (\theta) \right\| \leq \left\| P_1^0 (\theta') P_1^0 (\theta)' \right\| \left\| A_1^0 A_1^0 \right\|^{1/2} \left\| \hat{A}_{11} (\theta)' \hat{A}_{11} (\theta) \right\|^{1/2} \left\| V_1 (\theta) \right\|^2 = O_p (1)
$$

by Assumptions C1 and C2. In an analogous way, it can be shown that $\| \hat{H}_{21} (\theta) \| = O_p (1)$. By Loève’s inequality

$$
N^{-1} \sum_{t=1}^N \left\| V_1 (\theta) \left[ \hat{\lambda}_{tt} (\theta) - \hat{H}_{11} (\theta)' \lambda_{t1}^0 - \hat{H}_{21} (\theta)' \lambda_{t2}^0 \right] \right\|^2 \leq 4N^{-1} \sum_{t=1}^N \left[ \hat{\sigma}_{tt} (\theta) + \hat{\varphi}_{tt} (\theta) + \hat{\varphi}_{tt} (\theta) + \hat{\varphi}_{tt} (\theta) \right],
$$

where

$$
\hat{\sigma}_{tt} (\theta) = N^{-2} \left\| \sum_{t=1}^N \hat{\lambda}_{tt} (\theta) \sigma_{1tt} (\theta) \right\|^2, \quad \hat{\varphi}_{tt} (\theta) = N^{-2} \left\| \sum_{t=1}^N \hat{\lambda}_{tt} (\theta) \varphi_{1tt} (\theta) \right\|^2.
$$

Starting from $\hat{\sigma}_{tt} (\theta)$,

$$
N^{-1} \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \sigma_{1tt} (\theta) \right\|^2 \leq \left[ \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \right\|^2 \right] \left[ \sum_{t=1}^N \sigma_{1tt} (\theta) \right],
$$

and

$$
N^{-1} \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \varphi_{1tt} (\theta) \right\|^2 \leq \left[ \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \right\|^2 \right] \left[ \sum_{t=1}^N \sigma_{1tt} (\theta) \right].
$$

by Lemma A.1(a). As for $\hat{\varphi}_{tt} (\theta)$,

$$
N^{-1} \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \varphi_{1tt} (\theta) \right\|^2 = N^{-2} \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \varphi_{1tt} (\theta) \right\|^2
$$

$$
\leq \left\{ N^{-2} \sum_{t=1}^N \sum_{q=1}^N \left[ \hat{\lambda}_{tt} (\theta)' \hat{\lambda}_{tt} (\theta) \right]^2 \right\}^{1/2} \left\{ N^{-2} \sum_{t=1}^N \sum_{q=1}^N \left[ \hat{\lambda}_{tt} (\theta)' \hat{\lambda}_{tt} (\theta) \right] \varphi_{1tt} (\theta) \right\}^{1/2}
$$

$$
\leq \left\{ N^{-1} \sum_{t=1}^N \left\| \hat{\lambda}_{tt} (\theta) \right\|^2 \right\} \left\{ N^{-2} \sum_{t=1}^N \sum_{q=1}^N \left[ \hat{\lambda}_{tt} (\theta)' \hat{\lambda}_{tt} (\theta) \right] \varphi_{1tt} (\theta) \right\}^{1/2}.
$$

Since

$$
E \left\{ \left[ \sum_{t=1}^N \varphi_{1tt} (\theta) \right]^2 \right\} = E \left\{ \sum_{t=1}^T \sum_{q=1}^T \varphi_{1tt} (\theta) \varphi_{1tt} (\theta) \right\} \leq N^2 \max_{t,i} E |\varphi_{1tt} (\theta)|^4
$$

and

$$
E |\varphi_{1tt} (\theta)|^4 = T^{-1/2} E \left\{ \sum_{t=1}^T \varphi_{1tt} (\theta) \varepsilon_t \varepsilon_{tt} - E \left[ \varphi_{1tt} (\theta) \varepsilon_{tt} \right] \right\}^4 \leq T^{-2} M
$$

by Assumption C3(d), then

$$
\sum_{t=1}^N \hat{\varphi}_{tt} (\theta) \leq O_p (1) \sqrt{\frac{N^2}{T^2}} = O_p \left( \frac{N}{T} \right).
$$

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and \( N^{-1} \sum_{i=1}^{N} \hat{\xi}_{1i} (\theta) = O_p (T^{-1}) \). Regarding \( \hat{\varphi}_{1i} (\theta) \),

\[
\hat{\varphi}_{1i} (\theta) = N^{-2} \left[ \sum_{i=1}^{N} \lambda_{1i} (\theta) \varphi_{1i} (\theta) \right] ^2
\]

\[
= N^{-2} \left[ \sum_{i=1}^{N} \lambda_{1i} (\theta) \left( T^{-1} \sum_{i=1}^{N} \left\{ I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 + I_{2i} (\theta) \right] + I_{2i} (\theta) \right) \right] ^2
\]

\[
\leq N^{-2} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \lambda_{1i}^T \left[ T^{-1} \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 + T^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \lambda_{1i}^T \left[ T^{-1} \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 \right] \right] \right\| ^2
\]

\[
\leq \left\{ N^{-1} \sum_{i=1}^{N} \left( T^{-2} \left\| \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 \right\| ^2 \right) \right\} \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right)
\]

\[
+ \left\{ N^{-1} \sum_{i=1}^{N} \left( T^{-2} \left\| \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 \right\| ^2 \right) \right\} \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right)
\]

\[
\leq \left\{ N^{-1} \sum_{i=1}^{N} \left( T^{-2} \left\| \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 \right\| ^2 \right) \right\} \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right) \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right)
\]

\[
O_p (1)
\]

and

\[
N^{-1} \sum_{i=1}^{N} \hat{\varphi}_{1i} (\theta) = \left\{ N^{-1} \sum_{i=1}^{N} \left( T^{-2} \left\| \sum_{i=1}^{N} I_{1i} (\theta) \left[ \hat{\xi}_{1i} (\theta) \right]^2 \right\| ^2 \right) \right\} \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right) \lambda_{1i}^2 \left( \left\| \lambda_{1i} \right\| ^2 \left( N^{-1} \sum_{i=1}^{N} \left\| \lambda_{1i} (\theta) \right\| ^2 \right) \right)
\]

\[
O_p (1)
\]

by Assumptions C2 and C4. In an analogous way, it can be proved that

\[
N^{-1} \sum_{i=1}^{N} \hat{\varphi}_{1i} (\theta) = O_p (T^{-1})
\]

Combining all results above, we have

\[
N^{-1} \sum_{i=1}^{N} \left\| \varphi_{1i} (\theta) - \hat{\varphi}_{1i} (\theta) \right\|^2 = O_p (N^{-1}) + O_p (T^{-1})
\]

This completes the proof of the theorem. \( \blacksquare \)

**Proof of Theorem 3.3.** In order to prove the theorem, it is sufficient to prove that

\[
\lim_{N,T \to \infty} P \left[ S_{FA} (\theta) \leq S_{FA} (\theta^0) \right] = 0, \quad \forall \theta \neq \theta^0,
\]

where \( S_{FA} (\theta) \) is defined in (8). Consider the identity

\[
S_{FA} (\theta) - S_{FA} (\theta^0) = S_{FA} (\theta) - S_F \left[ A_{11}^0 \hat{H}_{11} (\theta) + A_{12}^0 \hat{H}_{21} (\theta) + A_{21}^0 \hat{H}_{22} (\theta) + A_{12}^0 \hat{H}_{12} (\theta) \right]
\]

\[
+ S_F \left[ A_{11}^0 \hat{H}_{11} (\theta) + A_{12}^0 \hat{H}_{21} (\theta) + A_{21}^0 \hat{H}_{22} (\theta) + A_{12}^0 \hat{H}_{12} (\theta) \right] - S_F \left[ A_{11}^0 \hat{H}_{11} (\theta^0) + A_{12}^0 \hat{H}_{21} (\theta^0) + A_{21}^0 \hat{H}_{22} (\theta^0) \right]
\]

\[
+ S_F \left[ A_{11}^0 \hat{H}_{11} (\theta^0) + A_{12}^0 \hat{H}_{21} (\theta^0) + A_{21}^0 \hat{H}_{22} (\theta^0) \right] - S_F (\theta^0)
\]

where \( S_F (A, \theta) \) is defined in (4). By Lemma A.2, \( S_{FA} (\theta) - S_F \left[ A_{11}^0 \hat{H}_{11} (\theta) + A_{12}^0 \hat{H}_{21} (\theta) + A_{21}^0 \hat{H}_{22} (\theta) + A_{12}^0 \hat{H}_{12} (\theta) \right] = O_p \left( \frac{C_{A}^1}{N^2} \right) \) for any \( \theta \), including \( \theta = \theta^0 \). Since \( A_{11}^0 \hat{H}_{11} (\theta^0) \) and \( A_{21}^0 \hat{H}_{22} (\theta^0) \) span the same column space as \( A_{11}^0 \) and \( A_{21}^0 \), respectively, we have

\[
S_F \left[ A_{11}^0 \hat{H}_{11} (\theta^0) + A_{12}^0 \hat{H}_{21} (\theta^0) \right] = S_F (A_{11}^0, A_{21}^0, \theta^0)
\]

and \( S_F \left[ A_{11}^0 \hat{H}_{11} (\theta) + A_{12}^0 \hat{H}_{21} (\theta) + A_{21}^0 \hat{H}_{22} (\theta) + A_{12}^0 \hat{H}_{12} (\theta) \right] - S_F (A_{11}^0, A_{21}^0, \theta^0) \) has a positive limit by Lemma A.3. This completes the proof of the theorem. \( \blacksquare \)

**Proof of Corollary 3.1.** Corollary 3.1 easily follows from Theorem 3.3 and the proof is omitted. \( \blacksquare \)
Proof of Lemma A.1. Consider $j = 1$ ($j = 2$ is analogous and omitted). As for (a), let $\rho_{1lt} (\theta) = \sigma_{1lt} (\theta) / \left[ \sigma_{1lt} (\theta) \sigma_{1lT} (\theta) \right]^{1/2}$ such that $|\rho_{1lt} (\theta)| \leq 1$: since $|\sigma_{1lt} (\theta)| \leq M$ for all $l$ by Assumption C3(c), then

$$N^{-1} \sum_{l=1}^{N} \sum_{t=1}^{T} \sigma_{lT}^2 (\theta) = N^{-1} \sum_{l=1}^{N} \sum_{t=1}^{T} \sigma_{1lt} (\theta) \sigma_{1lt} (\theta) \rho_{1lt}^2 (\theta) \leq MN^{-1} \sum_{l=1}^{N} \sum_{t=1}^{T} |\sigma_{1lt} (\theta) \sigma_{1lT} (\theta)|^{1/2} |\rho_{1lt} (\theta)| = MN^{-1} \sum_{l=1}^{N} \sum_{t=1}^{T} |\sigma_{1lt} (\theta)| \leq M^2$$

by Assumption C3(c). In order to prove (b), for $j = 1$ (the proof for $j = 2$ is analogous) it is sufficient to prove that

$$E[1_1 (\theta) x_{1l}]^4 \leq M$$

for all $(\theta, t, l)$: we then have

$$E[1_1 (\theta) x_{1l}]^4 = E \left[ 1_1 (\theta)^4 + 2 \sum_0 (0) \lambda_{ij} f_i^4 + e_{1l} \right]^4 \leq \lambda^4 E \left[ 1_1 (\theta) 1_1 (\theta)^4 + 2 \lambda^4 E \left[ 1_1 (\theta) 1_2 (\theta)^4 \right] + E \left[ 1_1 (\theta) e_{1l} \right]^4 \right] \leq M$$

by Assumptions C1, C2 and C3(a). As for (c), set $j = 1$ (the proof for $j = 2$ is analogous and omitted) and consider

$$E \left[ \left( T^{-1/2} \sum_{t=1}^{T} 1_1 (\theta) e_{1l} \right) \right]^2 \leq \lambda^2 T^{-1} \sum_{t=1}^{T} |e_{1l}| \leq \lambda^2 M$$

by Assumptions C2 and C3(b).

Proof of Lemma A.2. Given $\Delta_j (\theta)$ defined in (5), for $j = 1, 2$, define

$$P_{\Delta_j} (\theta) = \Delta_j (\theta) \left[ \Delta_j (\theta)^{\prime} \Delta_j (\theta) \right]^{-1} \Delta_j (\theta)^{\prime},$$

$$P_{\Delta_j} \tilde{H}_{jj} + \Delta_m \tilde{H}_{mx} (\theta) = \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right]$$

$$\times \left[ \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right] \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right] \right]^{-1}, \quad j, m = 1, 2,$n

$$\times \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right]^\prime,$n

so that

$$S_{\text{ESA}} (\theta) = (NT)^{-1} \sum_{t=1}^{T} x_t \left( I_N - \left[ 1_1 (\theta) P_{\Delta_1} (\theta) + 2 e_{1l} (\theta) P_{\Delta_2} (\theta) \right] \right) x_t$$

and

$$S_{\text{E}} \left[ \Delta_1^0 \tilde{H}_{11} (\theta) + \Delta_2^0 \tilde{H}_{21} (\theta), \Delta_1^0 \tilde{H}_{22} (\theta) + \Delta_2^0 \tilde{H}_{12} (\theta), \theta \right]$$

$$= \left( NT \right)^{-1} \sum_{t=1}^{T} x_t \left( I_N - \left[ 1_1 (\theta) P_{\Delta_1} \tilde{H}_{11} + \Delta_2^0 \tilde{H}_{21} (\theta) + 2 e_{1l} (\theta) P_{\Delta_2} \tilde{H}_{22} + \Delta_1^0 \tilde{H}_{12} (\theta) \right] \right) x_t,$n

where $S_{\text{ESA}} (\theta)$ and $S_{\text{E}} (\theta)$ are defined in (4) and (8), respectively: it follows that

$$S_{\text{ESA}} (\theta) - S_{\text{E}} \left[ \Delta_1^0 \tilde{H}_{11} (\theta) + \Delta_2^0 \tilde{H}_{21} (\theta), \Delta_1^0 \tilde{H}_{22} (\theta) + \Delta_2^0 \tilde{H}_{12} (\theta), \theta \right]$$

$$= \left( NT \right)^{-1} \sum_{t=1}^{T} x_t \left[ P_{\Delta_1} \tilde{H}_{11} + \Delta_2^0 \tilde{H}_{21} (\theta) - P_{\Delta_1} (\theta) \right] x_t + \left( NT \right)^{-1} \sum_{t=1}^{T} x_t \left[ P_{\Delta_2} \tilde{H}_{22} + \Delta_1^0 \tilde{H}_{12} (\theta) - P_{\Delta_2} (\theta) \right] x_t.$n

Let

$$D_{\Delta_j} (\theta) = N^{-1} \Delta_j (\theta)^{\prime} \Delta_j (\theta),$$

$$D_{\Delta_j} \tilde{H}_{jj} + \Delta_m \tilde{H}_{mx} (\theta) = N^{-1} \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right] \left[ \Delta_j^0 \tilde{H}_{jj} (\theta) + \Delta_m^0 \tilde{H}_{mx} (\theta) \right]^\prime.$$
so that for \(j = 1, 2\) and \(j \neq m\),

\[
P_{A_j} (\theta) - P_{A^0_j \mathbf{R}_{j+1} + A^0_m \mathbf{R}_{m,j}} = N^{-1} \tilde{A}_j (\theta) \left[ \mathbf{D}_{A_j} (\theta) \right]^{-1} \tilde{A}_j (\theta)'
\]

\[
- N^{-1} \left[ \mathbf{A}^0_j \mathbf{R}_{j,j} + A^0_m \mathbf{H}_{m,j} \right] \left[ \mathbf{D}_{A^0_j \mathbf{R}_{j,j} + A^0_m \mathbf{R}_{m,j}} (\theta) \right]^{-1} \left[ \mathbf{A}^0_j \mathbf{R}_{j,j} + A^0_m \mathbf{H}_{m,j} (\theta) \right]'
\]

\[
= N^{-1} \left[ \tilde{A}_j (\theta) - \mathbf{A}^0_j \mathbf{R}_{j,j} - \mathbf{A}^0_m \mathbf{H}_{m,j} \right] \left[ \mathbf{D}_{A_j} (\theta) \right]^{-1} \left[ \tilde{A}_j (\theta) - \mathbf{A}^0_j \mathbf{R}_{j,j} - \mathbf{A}^0_m \mathbf{H}_{m,j} (\theta) \right]'
\]

\[
+ N^{-1} \left[ \tilde{A}_j (\theta) - \mathbf{A}^0_j \mathbf{R}_{j,j} (\theta) - \mathbf{A}^0_m \mathbf{H}_{m,j} (\theta) \right] \left[ \mathbf{D}_{A_j} (\theta) \right]^{-1} \left[ \tilde{A}_j (\theta) - \mathbf{A}^0_j \mathbf{R}_{j,j} (\theta) - \mathbf{A}^0_m \mathbf{H}_{m,j} (\theta) \right]'
\]

\[
+ N^{-1} \mathbf{A}^0_j \mathbf{R}_{j,j} (\theta) + A^0_m \mathbf{H}_{m,j} (\theta) \left[ \mathbf{D}_{A_j} (\theta) \right]^{-1} \left[ \mathbf{A}^0_j \mathbf{R}_{j,j} + A^0_m \mathbf{H}_{m,j} (\theta) \right]^{-1}
\]

\[
\times \left[ \mathbf{A}^0_j \mathbf{R}_{j,j} + A^0_m \mathbf{H}_{m,j} (\theta) \right]'
\]

We consider the case \(j = 1\): the case \(j = 2\) is analogous and omitted. We have

\[
(NT)^{-1} \sum_{t=1}^{T} x_{2i1}^2 (\theta) \left[ P_{A_1} (\theta) - P_{A^0_1 \mathbf{R}_{1+1} + A^0_2 \mathbf{R}_{21}} \right] x_t
\]

\[
= (NT)^{-1} \sum_{t=1}^{T} x_{2i1}^2 (\theta) N^{-1} \left[ \tilde{A}_1 (\theta) - \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) - \mathbf{A}^0_2 \mathbf{R}_{21} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{A}_1 (\theta) - \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) - \mathbf{A}^0_2 \mathbf{R}_{21} \right] x_t
\]

\[
+ (NT)^{-1} \sum_{t=1}^{T} x_{2i1}^2 (\theta) N^{-1} \left[ \tilde{A}_1 (\theta) - \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) - \mathbf{A}^0_2 \mathbf{R}_{21} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{A}_1 (\theta) - \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) - \mathbf{A}^0_2 \mathbf{R}_{21} \right] x_t
\]

\[
+ (NT)^{-1} \sum_{t=1}^{T} x_{2i1}^2 (\theta) N^{-1} \left[ \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) + \mathbf{A}^0_2 \mathbf{R}_{21} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{A}_1 (\theta) - \mathbf{A}^0_1 \mathbf{R}_{11} (\theta) - \mathbf{A}^0_2 \mathbf{R}_{21} \right] x_t
\]

\[
= a_1 (\theta) + a_2 (\theta) + a_3 (\theta) + a_4 (\theta).
\]

Starting from \(a_1 (\theta)\),

\[
a_1 (\theta) = N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left\{ \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right]' \right\}
\]

\[
\times \left[ T^{-1} \sum_{t=1}^{T} x_{3i1} (\theta) x_{4i1} x_{5i1} \right]^{-1/2}
\]

\[
\leq \left\{ N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left[ \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right]' \right] \right\}^{1/2}
\]

\[
\times \left\{ N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left[ T^{-1} \sum_{t=1}^{T} x_{3i1} (\theta) x_{4i1} x_{5i1} \right]^{-1/2} \right\}^{1/2}
\]

\[
\leq \left\{ N^{-1} \sum_{i=1}^{N} \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \right\} \left\| \mathbf{D}_{A_1} (\theta) \right\| O_p (1)
\]

\[
= \left\{ N^{-1} \sum_{i=1}^{N} \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \right\} O_p (1)
\]

by Lemma A.1(b) and the fact that \(\left\| \mathbf{D}_{A_1} (\theta) \right\| = O_p (1)\), which is proved below: from Theorem 3.2 it follows that \(a_1 (\theta) = O_p \left( C_{NT}^{-2} \right)\) for all \(\theta\). As for \(a_2 (\theta)\),

\[
a_2 (\theta) = N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left\{ \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \left[ \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} + \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ T^{-1} \sum_{t=1}^{T} x_{3i1} (\theta) x_{4i1} x_{5i1} \right] \right\}
\]

\[
\leq \left\{ N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left[ \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \right\} \left\| \mathbf{D}_{A_1} (\theta) \right\| O_p (1)
\]

\[
= \left\{ N^{-1} \sum_{i=1}^{N} \left[ \tilde{A}_{1i} (\theta) - \tilde{H}_{11} (\theta)' \mathbf{X}_{1i} - \tilde{H}_{21} (\theta)' \mathbf{X}_{2i} \right] \left[ \mathbf{D}_{A_1} (\theta) \right]^{-1} \right\} O_p (1)
\]

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and $a_2(\theta) = O_p\left(C_{NT}^{-1}\right)$ for all $\theta$. In an analogous way it is proved that $a_3(\theta) = O_p\left(C_{NT}^{-1}\right)$ for all $\theta$. Finally,

$$a_4(\theta) = N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left( \| \hat{H}_{11}(\theta)' \lambda_{it}^0 + \hat{H}_{21}(\theta)' \lambda_{it}^2 \| \right) \left( \| \hat{D}_{A_1}(\theta) \|^{2} - \| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \|^{2} \right) \left( \| \hat{D}_{A_1}(\theta) \|^{2} - \| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \|^{2} \right)^{1/2}$$

$$\leq \left\{ N^{-2} \sum_{i=1}^{N} \sum_{t=1}^{T} \left( \| \hat{H}_{11}(\theta)' \lambda_{it}^0 + \hat{H}_{21}(\theta)' \lambda_{it}^2 \| \right)^2 \| \hat{H}_{11}(\theta)' \lambda_{it}^0 + \hat{H}_{21}(\theta)' \lambda_{it}^2 \|^2 \right\}^{1/2} \left\{ N^{-1} \sum_{i=1}^{N} \| \hat{H}_{11}(\theta)' \lambda_{it}^0 + \hat{H}_{21}(\theta)' \lambda_{it}^2 \|^2 \right\}^{1/2}$$

$$\leq \left\| \hat{D}_{A_1}(\theta) \right\|^{2} - \left\| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{2} \right\}^{1/2}$$

$$\leq \left\| \hat{D}_{A_1}(\theta) \right\|^{2} - \left\| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{2} \right\}^{1/2}$$

where $O_p(1)$ comes from Lemma A.1(b) and Assumptions C1 and C2. Now, $\left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\| = O_p\left(C_{NT}^{-1}\right)$ for all $\theta$: this is because

$$\left[ \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right] = \left[ \hat{A}_{1}(\theta)' \hat{A}_{1}(\theta) - \left\{ \hat{A}_{1}(\theta)' \hat{H}_{11}(\theta)' \hat{A}_{1}(\theta)' \right\} \right]$$

$$= \left\{ N^{-1} \sum_{i=1}^{N} \left[ \hat{A}_{1}(\theta)' \hat{H}_{11}(\theta)' \hat{A}_{1}(\theta)' \right] \right\}$$

so that

$$\left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\| \leq N^{-1} \sum_{i=1}^{N} \left[ \hat{A}_{1}(\theta)' \hat{H}_{11}(\theta)' \hat{A}_{1}(\theta)' \right]$$

and the result follows. In general,

$$\left[ \hat{D}_{A_1}(\theta) \right]^{-1} - \left[ \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right]^{-1} = \left[ \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right] \left[ \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right]^{-1}$$

and

$$\left\| \hat{D}_{A_1}(\theta) \right\|^{-1} - \left[ \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right]^{-1} \leq \left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\| \left\| \hat{D}_{A_1}(\theta) \right\|^{-1} \left\| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{-1} \right\| \left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{-1} \right\| \left\| \hat{D}_{A_1}(\theta) \right\|^{-1} \left\| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{-1} \right\| \cdot \left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{-1} \right\| \cdot \left\| \hat{D}_{A_1}(\theta) \right\|^{-1} \left\| \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\|^{-1} \right\|.$$

The matrix $A_{1}^{0}A_{0}^{0}/N$ converges to a positive definite matrix by Assumption C2, for $j = 1, 2$, and the rank of $\hat{H}_{11}(\theta)$ is equal to $R^0$ for all $\theta$: since the rank of $\hat{H}_{21}(\theta)$ is equal to $R^1$ for $\theta \neq \theta^0$, and $\hat{H}_{21}(\theta^0) = 0_{R^0}$, this implies that $\hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21}$ converges to a positive definite matrix. Since $\left\| \hat{D}_{A_1}(\theta) - \hat{D}_{A_1}^{H}\hat{H}_{11} + \hat{A}_{2}\hat{H}_{21} \right\| = O_p\left(C_{NT}^{-1}\right)$, $\hat{D}_{A_1}(\theta)$
also converges to a positive definite matrix: this implies that \[
\left\| B_{A_i}(\theta) \right\| = O_p(1) \]: therefore,

\[
\left\| B_{A_i}(\theta) \right\| = O_p\left( C_{N,T}^{-1} \right)
\]

and \(a_4(\theta) = O_p\left( C_{N,T}^{-1} \right)\) for all \(\theta\). Combining all above results, we have

\[
a_1(\theta) + a_2(\theta) + a_3(\theta) + a_4(\theta) = O_p\left( C_{N,T}^{-2} \right) + O_p\left( C_{N,T}^{-1} \right) + O_p\left( C_{N,T}^{-1} \right) + O_p\left( C_{N,T}^{-1} \right) = O_p\left( C_{N,T}^{-1} \right)
\]

this completes the proof of the lemma. ■

**Proof of Lemma A.3.** Let

\[
P_{A_i} = A_i^0 \left( A_i^0 A_i^0 \right)^{-1} A_i^0, \quad j = 1, 2,
\]

and recall \(P_{A_i R_i} + A_i^0 R_mj(\theta)\) as defined in (22). Write

\[
S_P \left[ A_i^0 \tilde{H}_{11}(\theta) + A_i^0 \tilde{H}_{21}(\theta) + A_i^0 \tilde{H}_{12}(\theta) + A_i^0 \tilde{H}_{22}(\theta) \right] = S_P \left( A_i^0, A_i^0, \theta \right)
\]

\[
(NT)^{-1} \sum_{t=1}^{T} \left\{ \left[ \tilde{1}_{1t}(\theta) \right] P_{A_i} - 1_{1t}(\theta) P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] + \left[ \tilde{2}_{1t}(\theta) \right] P_{A_i^0} - 1_{2t}(\theta) P_{A_i^0 \tilde{H}_{22} + A_i^0 \tilde{H}_{12}(\theta) \right] \}
\]

\[
(NT)^{-1} \sum_{t=1}^{T} \left\{ \left[ \tilde{1}_{1t}(\theta) \right] A_i^0 f_i^0 + 1_{2t}(\theta) A_i^0 f_i^0 + e_i \right\}
\]

\[
= b_1(\theta) + b_2(\theta) + b_3(\theta),
\]

where

\[
b_1(\theta) = (NT)^{-1} \sum_{t=1}^{T} \left[ \tilde{1}_{1t}(\theta) \right] I_{1t}(\theta) \left[ A_i^0 P_{A_i} - A_i^0 P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
+ (NT)^{-1} \sum_{t=1}^{T} \left[ I_{2t}(\theta) 1_{1t}(\theta) \right] \left[ A_i^0 P_{A_i} - A_i^0 P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
+ (NT)^{-1} \sum_{t=1}^{T} \left[ I_{2t}(\theta) I_{2t}(\theta) \right] \left[ A_i^0 P_{A_i} - A_i^0 P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
+ (NT)^{-1} \sum_{t=1}^{T} \left[ I_{2t}(\theta) I_{2t}(\theta) \right] \left[ A_i^0 P_{A_i} - A_i^0 P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
= b_{11}(\theta) + b_{12}(\theta) + b_{13}(\theta) + b_{14}(\theta),
\]

\[
b_2(\theta) = 2(NT)^{-1} \sum_{t=1}^{T} \left[ \tilde{2}_{1t}(\theta) I_{1t}(\theta) \right] \left[ e_i^A P_{A_i} - e_i^A P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
+ 2(NT)^{-1} \sum_{t=1}^{T} \left[ I_{2t}(\theta) I_{2t}(\theta) \right] \left[ e_i^A P_{A_i} - e_i^A P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
+ 2(NT)^{-1} \sum_{t=1}^{T} \left[ I_{2t}(\theta) I_{2t}(\theta) \right] \left[ e_i^A P_{A_i} - e_i^A P_{A_i^0 \tilde{H}_{11} + A_i^0 \tilde{H}_{21} + A_i^0 \tilde{H}_{12} + A_i^0 \tilde{H}_{22}(\theta) \right] A_i^0 f_i^0 \right]
\]

\[
= b_{21}(\theta) + b_{22}(\theta) + b_{23}(\theta) + b_{24}(\theta),
\]

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and
\[
\begin{aligned}
b_3(\theta) &= (NT)^{-1} \sum_{t=1}^{T} e_t' [z_{1t}(\theta) - z_{1t}(\theta)] P_{A_t^0 e_t} \\
&+ (NT)^{-1} \sum_{t=1}^{T} e_t' [z_{2t}(\theta) - z_{2t}(\theta)] P_{A_t^0 e_t} \\
&+ (NT)^{-1} \sum_{t=1}^{T} e_t' [z_{3t}(\theta)] P_{A_t^0 - P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta)} e_t \\
&+ (NT)^{-1} \sum_{t=1}^{T} e_t' [z_{4t}(\theta)] P_{A_t^0 - P_{A_t^0 H_{22} + A_t^0 H_{12}}(\theta)} e_t \\
&= b_{31}(\theta) + b_{32}(\theta) + b_{33}(\theta) + b_{34}(\theta).
\end{aligned}
\]

Consider \( b_1(\theta) \) first. We have
\[
\begin{aligned}
b_{11}(\theta) &= \text{tr} \left\{ N^{-1} \left[ A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right] \left[ T^{-1} \sum_{t=1}^{T} I_{1t}(\theta) I_{1t}(\theta) f_{t}^0 f_{t}^0 \right] \right\} \\
&= \text{tr} \left\{ N^{-1} \left[ A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right] \left[ T^{-1} \sum_{t=1}^{T} z_{1t}(\theta) z_{1t}(\theta) f_{t}^0 f_{t}^0 \right] \right\} \\
&= \text{tr} \left\{ \Sigma_{1t}(\theta) \left[ \Sigma_{1t}(\theta) - \Sigma_{1t}(\theta) \right] \right\},
\end{aligned}
\]
where \( \Sigma_{1t}(\theta) = \text{p} \lim_{N \to \infty} \left\{ N^{-1} A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right\} \).

Now \( \Sigma_{1t}(\theta) \) is different from zero by Assumption C2 and it is also positive semi-definite. The matrix \( \Sigma_{1t}(\theta, \theta^0) \) is positive definite by Assumption C1. It then follows that
\[
\text{p} \lim_{N, T \to \infty} b_{11}(\theta) = \text{tr} \left( \Sigma_{1t}(\theta, \theta^0) \right) > 0.
\]

Consider now
\[
\begin{aligned}
b_{12}(\theta) &= \text{tr} \left\{ N^{-1} \left[ A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right] \left[ T^{-1} \sum_{t=1}^{T} I_{1t}(\theta) I_{1t}(\theta) f_{t}^0 f_{t}^0 \right] \right\} \\
&= \text{tr} \left\{ N^{-1} \left[ A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right] \left[ T^{-1} \sum_{t=1}^{T} z_{1t}(\theta) z_{1t}(\theta) f_{t}^0 f_{t}^0 \right] \right\} \\
&= \text{tr} \left\{ \Sigma_{1t}(\theta) \left[ \Sigma_{1t}(\theta) - \Sigma_{1t}(\theta) \right] \right\},
\end{aligned}
\]
where \( \Sigma_{1t}(\theta) = \text{p} \lim_{N \to \infty} \left\{ N^{-1} A_{t}^{0} P_{A_t^0} A_t^0 - A_{t}^{0} P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 \right\} \); taking into account Assumption C1, it follows that
\[
\text{p} \lim_{N, T \to \infty} b_{12}(\theta) \geq 0.
\]
In a similar way it is proved that \( \text{p} \lim_{N, T \to \infty} b_{13}(\theta) \geq 0 \) and \( \text{p} \lim_{N, T \to \infty} b_{14}(\theta) \geq 0 \). Then
\[
\text{p} \lim_{N \to \infty} b_{1}(\theta) = \text{p} \lim_{N \to \infty} b_{11}(\theta) + \text{p} \lim_{N \to \infty} b_{12}(\theta) + \text{p} \lim_{N \to \infty} b_{13}(\theta) + \text{p} \lim_{N \to \infty} b_{14}(\theta) > 0, \quad \forall \theta \neq \theta^0.
\]

Consider now \( b_2(\theta) \). We have
\[
\begin{aligned}
b_{23}(\theta) &= 2 (NT)^{-1} \sum_{t=1}^{T} \sum_{t=1}^{T} I_{1t}(\theta) I_{1t}(\theta) e_t' P_{A_t^0} A_t^0 f_{t}^0 - 2 (NT)^{-1} \sum_{t=1}^{T} \sum_{t=1}^{T} z_{1t}(\theta) z_{1t}(\theta) e_t' P_{A_t^0 H_{11} + A_t^0 H_{21}}(\theta) A_t^0 f_{t}^0.
\end{aligned}
\]

By Lemma A.1(c) and Assumption C1,
\[
\begin{aligned}
|\text{p} \lim_{N \to \infty} \sum_{t=1}^{T} z_{1t}(\theta) z_{1t}(\theta) e_t' P_{A_t^0} A_t^0 f_{t}^0| &= |\text{p} \lim_{N \to \infty} \sum_{t=1}^{T} z_{1t}(\theta) z_{1t}(\theta) e_t' A_t^0 f_{t}^0| \\
&\leq \left| \text{p} \lim_{N \to \infty} \sum_{t=1}^{T} \sum_{t=1}^{T} z_{1t}(\theta) f_{t}^0 \right|^{1/2} N^{-1/2} \left| \text{p} \lim_{N \to \infty} \sum_{t=1}^{T} z_{1t}(\theta) e_t' A_t^0 f_{t}^0 \right|^{1/2} \\
&= o_p \left( \frac{1}{\sqrt{N}} \right).
\end{aligned}
\]
Further, 

\[(NT)^{-1} \sum_{t=1}^{T} I_{1t}(\theta) I_{2t}(\theta^{0}) e_{t}^H P_{A_{ij}^H} \mathbf{H}_{11} + A_{ij}^H \mathbf{H}_{21}(\theta) A_{ij}^H = O_p \left( \frac{1}{\sqrt{N}} \right). \]

Therefore, \( b_{21}(\theta) = O_p \left( \frac{1}{\sqrt{N}} \right). \) In an analogous way, it can be proved that \( b_{22}(\theta) = O_p \left( \frac{1}{\sqrt{N}} \right), \) \( b_{23}(\theta) = O_p \left( \frac{1}{\sqrt{N}} \right), \) \( b_{24}(\theta) = O_p \left( \frac{1}{\sqrt{N}} \right). \) Therefore, \( b_{2}(\theta) = O_p \left( \frac{1}{\sqrt{N}} \right), \) \( \frac{N}{T} \to 0 \) as \( N \to \infty. \)

Finally, consider \( b_{3}(\theta). \) We have, \( b_{31}(\theta) = o_p(1) \) and \( b_{32}(\theta) = o_p(1). \) Further, \( [P_{A_{ij}^H} - P_{A_{ij}^H} \mathbf{H}_{11} + A_{ij}^H \mathbf{H}_{21}(\theta)] \) and \( [P_{A_{ij}^H} - P_{A_{ij}^H} \mathbf{H}_{12} + A_{ij}^H \mathbf{H}_{12}(\theta)] \) are positive semi-definite matrices, which implies that \( b_{33}(\theta) \geq 0 \) and \( b_{34}(\theta) \geq 0: \) this implies that \( \lim_{N,T \to \infty} b_{3}(\theta) \geq 0. \) This completes the proof of the lemma. 

A.2 Proofs of Results in Section 3.5

Let

\[ g_{ij}^0(\theta_1, \theta_2) = \|I_{2t}(\theta_2) - I_{2t}(\theta_1)\|{1 \leq i, \ldots, N, \quad t = 1, \ldots, T}, \]

\[ g_{ij}^0(\theta_1, \theta_2) = \|I_{2t}(\theta_2) - I_{2t}(\theta_1)\|{1 \leq i, \ldots, N, \quad t = 1, \ldots, T}, \]

\[ w_{ij}^0(\theta) = \|I_{2t}(\theta) - I_{2t}(\theta^0)\|{1 \leq i, \ldots, N, \quad t = 1, \ldots, T}, \]

\[ w^0(\alpha^0, \theta) = \frac{1}{N^{\alpha^0}} \sum_{t=1}^{T} w_{ij}^0(\theta), \]

\[ h^0(\alpha^0, \theta) = \frac{1}{N^{\alpha^0}} \sum_{t=1}^{T} I_{2t}(\theta) \delta^0 f_i c_{it}. \]

Lemma A.4 There exists a \( C_1 < \infty \) such that for all \( \theta_L \leq \theta_1 \leq \theta_2 \leq \theta_U \) and \( s \leq 4, \)

\[ E \left\{ g_{ij}^0(\theta_1, \theta_2)^s \right\} \leq C_1 |\theta_2 - \theta_1|, \quad i = 1, \ldots, N, \]

(23)

and

\[ E \left\{ g_{ij}^0(\theta_1, \theta_2)^s \right\} \leq C_1 |\theta_2 - \theta_1|. \]

(24)

Lemma A.5 There exists a \( K < \infty \) such that for all \( \theta_L \leq \theta_1 \leq \theta_2 \leq \theta_U, \)

\[ E \left[ \frac{1}{\sqrt{T}} \sum_{t=1}^{T} \left\{ g_{ij}^0(\theta_1, \theta_2)^s - E \left\{ g_{ij}^0(\theta_1, \theta_2)^s \right\} \right\} \right] \leq K |\theta_2 - \theta_1|. \]

Lemma A.6 There exist constants \( B > 0 \) and \( 0 < d < \infty \) such that for all \( \eta > 0 \) and \( \varepsilon > 0, \) there exists a \( \bar{v} < \infty \) such that for all \( N \) and \( T, \)

\[ \Pr \left[ \inf_{\theta^0 \in [-\theta - \theta^0, \theta - \theta^0]} \frac{w^0(\alpha^0, \theta)}{|\theta - \theta^0|} < (1 - \eta) d \right] \leq \varepsilon. \]

Lemma A.7 For all \( \eta > 0 \) and \( \varepsilon > 0, \) there exists some \( \bar{v} < \infty \) such that for any \( B < \infty, \)

\[ \Pr \left[ \sup_{\theta^0 \in [-\theta - \theta^0, \theta - \theta^0]} \frac{\|h^0(\alpha^0, \theta) - h^0(\alpha^0, \theta^0)\|}{|\theta - \theta^0|} > \eta \right] \leq \varepsilon. \]

Proof of Theorem 3.4. Let \( B \) and \( d \) be defined as in Lemma A.6. Pick \( \eta > 0 \) small enough so that

\[(1 - \eta) d - 2\eta > 0. \]
Let $\mathbb{E}_{NT}$ be the joint event that $|\hat{\theta} - \theta^0| \leq B$, $\left\| \hat{\mathbf{f}}_{j,t} - \mathbf{f}_0^{j,t} \right\|$ is small enough so that (28) below is satisfied, for $j = 1, 2$, $i = 1, \ldots, N$, $t = 1, \ldots, T$, and
\[
\frac{\varepsilon}{N^{1/T}} \inf_{|\theta - \theta^0| \leq B} \frac{w_0(\alpha, \theta)}{|\theta - \theta^0|} \geq (1 - \eta) d,
\]
and
\[
\frac{\varepsilon}{N^{1/T}} \sup_{|\theta - \theta^0| \leq B} \frac{\| \mathbf{h}^0(\alpha, \theta) - \mathbf{h}^0(\alpha, \theta^0) \|}{|\theta - \theta^0|} \leq \eta.
\]

Fix $\varepsilon > 0$ and pick $v, \bar{N}$ and $\tilde{T}$ so that $\Pr(\mathbb{E}_{NT}) \geq 1 - \varepsilon$ for all $N \geq \bar{N}$ and $T \geq \tilde{T}$, which is possible under Corollary 3.1, and Lemmas A.6 and A.7. Given $S(\mathbf{A}, \mathbf{F}, \theta)$ defined in (2), let
\[
S(\alpha, \mathbf{A}, \mathbf{F}, \theta) = \frac{1}{N^{1/T}} \sum_{t=1}^{T} \left[ x_t - A_1 f_t - \Delta f_{2t}(\theta) \right]' \left[ x_t - A_1 f_t - \Delta f_{2t}(\theta) \right]
\]
for $j = 1, 2$, $i = 1, \ldots, N$, $t = 1, \ldots, T$, it follows that
\[
S(\alpha, \tilde{A}, \tilde{F}, \theta) - S(\alpha, \hat{A}, \hat{F}, \theta^0) = D \left[ S(\alpha, \mathbf{A}, \mathbf{F}, \theta) - S(\alpha, \mathbf{A}, \mathbf{F}, \theta^0) \right],
\]
for some $D > 0$, where $\tilde{f}_{2t}(\theta) = \tilde{f}_{2t}(\theta) \tilde{f}_t$, $\tilde{A} = \tilde{A}_2 - \tilde{A}_1$, $\tilde{f}_0^{j,t}(\theta) = \tilde{f}_0^{j,t}(\theta)$ and $\Delta_0 = \Delta_0^j - \Delta_0^0$: the sign of $S(\alpha, \tilde{A}, \tilde{F}, \theta) - S(\alpha, \hat{A}, \hat{F}, \theta^0)$ is then equal to the sign of $S(\alpha, \mathbf{A}, \mathbf{F}, \theta) - S(\alpha, \mathbf{A}, \mathbf{F}, \theta^0)$. We have
\[
S(\alpha, \mathbf{A}, \mathbf{F}, \theta) - S(\alpha, \mathbf{A}, \mathbf{F}, \theta^0) = \frac{1}{N^{1/T}} \sum_{t=1}^{T} \left[ \mathbf{f}_0^{j,t}(\theta) - \mathbf{f}_0^{j,t}(\theta^0) \right]' \Delta_0^j \Delta_0^0 \left[ \mathbf{f}_0^{j,t}(\theta) - \mathbf{f}_0^{j,t}(\theta^0) \right]
\]
and
\[
S(\alpha, \mathbf{A}, \mathbf{F}, \theta) - S(\alpha, \mathbf{A}, \mathbf{F}, \theta^0) = \frac{1}{N^{1/T}} \sum_{t=1}^{T} \left[ \mathbf{f}_0^{j,t}(\theta) - \mathbf{f}_0^{j,t}(\theta^0) \right]' \Delta_0^j \Delta_0^0 \left[ \mathbf{f}_0^{j,t}(\theta) - \mathbf{f}_0^{j,t}(\theta^0) \right]
\]
Suppose $\theta \in [\theta^0 + \varepsilon N^{-\alpha T^{-1}}, \theta^0 + B]$ and that event $\mathbb{E}_{NT}$ holds. It follows that
\[
S_1(\alpha, \theta) = \frac{1}{N^{1/T}} \sum_{t=1}^{T} \sum_{i=1}^{N} \left[ \mathbf{f}_0^{i,t}(\theta) - \mathbf{f}_0^{i,t}(\theta^0) \right]' \Delta_0^i \Delta_0^0 \left[ \mathbf{f}_0^{i,t}(\theta) - \mathbf{f}_0^{i,t}(\theta^0) \right]
\]
(30)
and

\[
\frac{S^2_{t} (\alpha^0, \theta)}{\theta - \theta^0} = -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \Delta^0 e_t
\]

\[
= -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

\[
\geq -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

\[
= -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

\[
\geq -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

\[
= -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

\[
= -\frac{1}{N^a T} \left| \theta - \theta^0 \right| \sum_{i=1}^{T} \sum_{l=1}^{K} \left( f^0_{2t} (\theta) - f^0_{2t} (\theta^0) \right)^2 \delta^0 e_{lt}
\]

By (25) through (31) it follows that for some \( D > 0, \)

\[
S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta \right) - S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta^0 \right) \geq D \left[ \frac{\theta^0 (\alpha^0, \theta) - \theta^0 (\alpha^0, \theta^0)}{\theta - \theta^0} \right] - 2 \left[ \frac{\theta^0 (\alpha^0, \theta) - \theta^0 (\alpha^0, \theta^0) \eta}{\theta - \theta^0} \right] \geq D \left( 1 - \eta \right) d - 2\eta \geq 0.
\]

Given the event \( \mathbb{E}_{NT}, \) if \( \theta \in \left[ \theta^0 + \delta N^{-a} T^{-1}, \theta^0 + \delta \right] \) then \( S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta \right) - S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta^0 \right) > 0. \) In a similar way, it can be shown that if \( \theta \in \left[ \theta^0 - \delta N^{-a} T^{-1}, \theta^0 - \delta \right] \) then \( S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta \right) - S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta^0 \right) > 0. \) As \( S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta \right) - S \left( \alpha^0, \tilde{A}, \tilde{F}, \theta^0 \right) \leq 0, \) if \( \mathbb{E}_{NT} \) occurs then \( \theta - \theta^0 \leq \delta N^{-a} T^{-1}. \) Since \( \operatorname{Pr} \left( \mathbb{E}_{NT} \right) \geq 1 - \epsilon \) for \( N \geq \tilde{N} \) and \( T \geq \tilde{T}, \) then \( \operatorname{Pr} \left( \theta - \theta^0 > \delta N^{-a} T^{-1} \right) \leq \epsilon \) for \( N \geq \tilde{N} \) and \( T \geq \tilde{T}. \) This is sufficient to show that \( N^a T \left( \theta - \theta^0 \right) = O_p \left( 1 \right). \) The convergence rate of the estimator for the loadings follows from (11). \( \blacksquare \)

**Proof of Corollary 3.2.** Corollary 3.2 easily follows from Theorem 3.4 and the proof is omitted.\( \blacksquare \)

**Proof of Lemma A.4.** We show (23): the proof of (24) is analogous. Given a random matrix \( A, \)

\[
\frac{\partial}{\partial \theta} E \left[ \mathcal{A} \mathcal{I}_{11} (\theta) \right] = E \left( \mathcal{A} \mathcal{I}_{11} | z_1 = \theta \right) f_Z (\theta).
\]

Under Assumption CR(b)

\[
\frac{\partial}{\partial \theta} E \left[ \left\| f^0_{e1} \right\|^2 \mathcal{I}_{11} (\theta) \right] = E \left( \left\| f^0_{e1} \right\|^2 | z_1 = \theta \right) f_Z (\theta) \leq E \left( \left\| f^0_{e1} \right\|^4 | z_1 = \theta \right) f_Z (\theta) \leq C_{11} | \theta - \theta^0 | c \leq C_{11} | \theta - \theta^0 | c.
\]

where \( C_1 = \max \left| 1, C \right| \). For \( \theta_1 \leq \theta_2, \mathcal{I}_{11} (\theta_2) - \mathcal{I}_{11} (\theta_1) \) is either equal to one or to zero: by a first-order Taylor expansion, it follows that

\[
E \left[ \left( \theta_1 (\theta_2) \theta_2 \right) \right] = E \left[ \theta_2 - \theta_1 \right] \left\| f^0_{e1} \right\|^2 \leq C_{11} | \theta_2 - \theta_1 | c.
\]

**Proof of Lemma A.5.** Lemma 3.4 in Peligrad (1982) shows that under Assumption CR(a) there exists a \( K' < \infty \) such that, taking into account (24) in Lemma A.4,

\[
E \left[ \left\| \frac{1}{\sqrt{T}} \sum_{t=1}^{T} \left( \left\| \mathcal{A} \mathcal{I}_{2t} (\theta_1, \theta_2) \right\|^2 - E \left( \left\| \mathcal{A} \mathcal{I}_{2t} (\theta_1, \theta_2) \right\|^2 \right) \right) \right\|^2 \right] \leq K' E \left( \left\| \left( \mathcal{A} \mathcal{I}_{2t} (\theta_1, \theta_2) \right) - E \left( \mathcal{A} \mathcal{I}_{2t} (\theta_1, \theta_2) \right) \right\|^2 \right) \]

\[
\leq 2K' \left( \left\| \left( \mathcal{A} \mathcal{I}_{2t} (\theta_1, \theta_2) \right) \right\|^4 \right)
\]

\[
\leq 2K' C_{11} | \theta_2 - \theta_1 | c.
\]

setting \( K = 2K' C_{11} \) completes the proof of the lemma.\( \blacksquare \)
Proof of Lemma A.6. For $\theta \geq \theta^0$,

$$
E \left[ w^0 (\alpha^0, \theta) \right] = \frac{1}{N \nu^0} \sum_{i=1}^{N} E \left[ w_{it}^0 (\theta) \right] \\
= \frac{1}{N \nu^0} \sum_{i=1}^{N} E \left[ w_{it}^0 (\theta) \right] + \frac{1}{N \nu^0} \sum_{i=N \nu^0 + 1}^{N} E \left[ w_{it}^0 (\theta) \right] \\
= \frac{1}{N \nu^0} \sum_{i=1}^{N \nu^0} \delta_i^0 \left[ \Sigma_{2t}^0 (\theta^0, \theta^0) - \Sigma_{2t}^0 (\theta, \theta) \right] \delta_i^0 + \frac{1}{N \nu^0} \sum_{i=N \nu^0 + 1}^{N} \delta_i^0 \left[ \Sigma_{2t}^0 (\theta^0, \theta^0) - \Sigma_{2t}^0 (\theta, \theta) \right] \delta_i^0,
$$

and

$$
\frac{\partial E \left[ w^0 (\alpha^0, \theta) \right]}{\partial \theta} = \frac{1}{N \nu^0} \sum_{i=1}^{N \nu^0} \delta_i^0 \mathbf{D}_{i}^0 (\theta) \mathbf{f}_2 (\theta) \delta_i^0 + \frac{1}{N \nu^0} \sum_{i=N \nu^0 + 1}^{N} \delta_i^0 \mathbf{D}_{i}^0 (\theta) \mathbf{f}_2 (\theta) \delta_i^0
$$

by (32) (the sign is reversed if $\theta \leq \theta^0$). By Assumptions CR(c) and CR(d), $\partial E \left[ w^0 (\alpha^0, \theta) \right] / \partial \theta$ is continuous at $\theta = \theta^0$, and $\partial E \left[ w^0 (\alpha^0, \theta) \right] / \partial \theta > 0$, respectively: there then exists a $B$ small enough such that for $|\theta - \theta^0| \leq B$

$$
d = \min_{|\theta - \theta^0| \leq B} \frac{\partial E \left[ w^0 (\alpha^0, \theta) \right]}{\partial \theta} > 0.
$$

The first-order Taylor expansion of $E \left[ w^0 (\alpha^0, \theta) \right]$ about $\theta = \theta^0$ results in

$$
\inf_{|\theta - \theta^0| \leq B} E \left[ w^0 (\alpha^0, \theta) \right] \geq d |\theta - \theta^0|,
$$

(33)
since $E \left[ w^0 (\alpha^0, \theta^0) \right] = 0$. Without loss of generality, set $\delta_i^0 = 0$, for $i = N \nu^0 + 1, \ldots, N$. Notice that

$$
E \left\{ \left[ w^0 (\alpha^0, \theta) - E \left[ w^0 (\alpha^0, \theta) \right] \right]^2 \right\} = E \left\{ \left[ \frac{1}{N \nu^0} \frac{1}{T} \sum_{t=1}^{T} \sum_{i=1}^{N} \left\{ w_{it}^0 (\theta) - E \left[ w_{it}^0 (\theta) \right] \right\} \right]^2 \right\} \\
= E \left\{ \left[ \frac{1}{N \nu^0} \frac{1}{T} \sum_{t=1}^{T} \sum_{i=1}^{N \nu^0} \left\{ w_{it}^0 (\theta) - E \left[ w_{it}^0 (\theta) \right] \right\} \right]^2 \right\} \\
\leq \frac{C_2}{N^{2 \nu^0}} \sum_{i=1}^{N \nu^0} E \left\{ \left[ \frac{1}{T} \sum_{t=1}^{T} \left\{ w_{it}^0 (\theta) - E \left[ w_{it}^0 (\theta) \right] \right\} \right]^2 \right\} \leq \frac{C_2}{N^{2 \nu^0}} \sum_{i=1}^{N \nu^0} \left\| \mathbf{L}_{i} \mathbf{L}^t \right\|^2 \leq \frac{C_2}{N^{2 \nu^0}} \sum_{i=1}^{N \nu^0} \left\| \mathbf{L}_{i} \mathbf{L}^t \right\|^2 \leq 2 \lambda_i, \quad i = 1, \ldots, N \nu^0,
$$

for some $C_2 < \infty$, and

$$
E \left\{ \left[ \frac{1}{T} \sum_{t=1}^{T} \left\{ w_{it}^0 (\theta) - E \left[ w_{it}^0 (\theta) \right] \right\} \right]^2 \right\} \leq \left\| \delta_i^0 \right\|^4 \frac{1}{T} \sum_{i=1}^{T} \left\{ \left\| \mathbf{L}_{i} \mathbf{L}^t \right\|^2 \right\}, \quad i = 1, \ldots, N \nu^0,
$$

by Lemma A.5: since

$$
\left\| \delta_i^0 \right\| = \left\| \mathbf{L}_{i} \right\| - \left\| \mathbf{L}_{i} \right\| \leq \left\| \mathbf{L}_{i}^t \right\| + \left\| \mathbf{L}_{i} \right\| \leq 2 \lambda_i, \quad i = 1, \ldots, N \nu^0,
$$

by Assumption C2, it follows that

$$
E \left\{ \left[ w^0 (\alpha^0, \theta) - E \left[ w^0 (\alpha^0, \theta) \right] \right]^2 \right\} \leq \frac{C_2 16 \lambda^4}{N^{2 \nu^0} \nu^0} K \left| \theta - \theta^0 \right|.
$$

(34)

For any $\eta$ and $\varepsilon$, set

$$
b = \frac{1 - \eta/2}{1 - \eta} > 1
$$

(36)

and

$$
\bar{\varepsilon} = \frac{8 C_2 16 \lambda^4 K}{\eta^2 d^2 (1 - 1/b)^2 \varepsilon}.
$$

(37)
Assume $N$ and $T$ large enough so that $\bar{v}/\left(N^{a_0} T\right) \leq B$, otherwise the lemma is trivially satisfied. For $l_N = 1, \ldots, N + 1$ and $l_T = 1, \ldots, T + 1$, set $\theta_{l_N, l_T} = \theta^0 + \bar{v}b^{N-1}b^{T-1}/\left(N^{a_0} T\right)$, where $N$ and $T$ are integers such that $\theta_{N,T} - \theta^0 = \bar{v}b^{N-1}b^{T-1}/\left(N^{a_0} T\right) \leq B$, $\theta_{N+1,T} - \theta^0 > B$ and $\theta_{N,T+1} - \theta^0 > B$ (since $\bar{v}/\left(N^{a_0} T\right) \leq B$ then $NT \geq 1$). By Markov’s inequality, (33), (35) and (37),

$$\Pr\left\{ \sup_{1 \leq N \leq N, \frac{1}{2} \leq l_T \leq T} \left| \frac{w^0(\alpha^0, \theta_{l_N, I_T})}{E[w^0(\alpha^0, \theta_{l_N, I_T})]} - 1 \right| > \frac{\eta}{2} \right\} \leq \left( \frac{2}{\eta} \right)^{2} \sum_{N=1}^{\infty} \sum_{l_T=1}^{T} \frac{E\left[\left| w^0(\alpha^0, \theta_{l_N, I_T}) - E[w^0(\alpha^0, \theta_{l_N, I_T})]\right|^2 \right]}{E\left[w^0(\alpha^0, \theta_{l_N, I_T})\right]^2} \leq \frac{4}{\eta^2} \sum_{N=1}^{\infty} \sum_{l_T=1}^{T} \frac{C_2 N^{-a_0} T^{-1} 16 \lambda^4 K (\theta_{l_N, I_T} - \theta^0)}{d^2 (\theta_{l_N, I_T} - \theta^0)^2} \leq \frac{4}{\eta^2} \sum_{N=1}^{\infty} \sum_{l_T=1}^{T} \frac{1}{d^2} \left( \sum_{l_T=0}^{\infty} \frac{1}{b^{l_T}} \right) \left( \sum_{l_T=0}^{\infty} \frac{1}{b^{l_T}} \right) \leq \frac{\varepsilon}{2},$$


it follows that for all $1 \leq l_N \leq N$ and $1 \leq l_T \leq T$, and with probability greater than $1 - \varepsilon/2$,

$$\left| \frac{w^0(\alpha^0, \theta_{l_N, I_T})}{E[w^0(\alpha^0, \theta_{l_N, I_T})]} - 1 \right| \leq \frac{\eta}{2}. \quad (38)$$

Using (36), for any $\theta$ such that $\bar{v}/\left(N^{a_0} T\right) \leq (\theta - \theta^0) \leq B$, there exists some $l_N \leq N$ and $l_T \leq T$ such that $\theta_{l_N, l_T} < \theta < \min \left\{ \theta_{l_N+1, l_T}, \theta_{l_N, l_T+1} \right\}$ and on the event (38)

$$\frac{w^0(\alpha^0, \theta)}{(\theta - \theta^0)} \geq \frac{w^0(\alpha^0, \theta_{l_N, l_T})}{E[w^0(\alpha^0, \theta_{l_N, l_T})]} \left[ \min \left\{ \theta_{l_N+1, l_T}, \theta_{l_N, l_T+1} \right\} - \theta^0 \right] \geq \left( 1 - \frac{\eta}{2} \right) \min \left\{ \theta_{l_N+1, l_T}, \theta_{l_N, l_T+1} \right\} - \theta^0 \geq (1 - \eta) \frac{d (\theta_{l_N, l_T} - \theta^0)}{\min \left\{ \theta_{l_N+1, l_T}, \theta_{l_N, l_T+1} \right\} - \theta^0} = (1 - \eta) d$$

where we set $(\theta_{l_N, l_T} - \theta^0)/\left[ \min \left\{ \theta_{l_N+1, l_T}, \theta_{l_N, l_T+1} \right\} - \theta^0 \right] = 1/b$: this event has probability greater than $1 - \varepsilon/2$ and then

$$\Pr \left\{ \frac{\bar{v}}{N^{a_0} T} \inf_{(\theta - \theta^0) \leq B} \frac{w^0(\alpha^0, \theta)}{(\theta - \theta^0)} < (1 - \eta) d \right\} \leq \frac{\varepsilon}{2},$$

holds. Taking the infimum over $-\bar{v}/\left(N^{a_0} T\right) \geq (\theta - \theta^0) \geq -B$ allows to prove a similar inequality using the same argument: this completes the proof of the lemma.

**Proof of Lemma A.7.** Given some $C_3 < \infty$ to be determined later, fix $\eta > 0$ and set

$$\bar{v} = \frac{8}{(0.5)^2 (0.5)^3} \frac{C_3 \lambda^2}{\eta^2 \varepsilon}. \quad (39)$$
For \( l_N = 1, \ldots, N \) and \( l_T = 1, \ldots, T \), set \( \theta_{l_Nl_T} - \theta^0 = -v^{2N-1-2^T-1} / \left( N^oT \right) \leq B \). Without loss of generality, assume that \( \delta_i^0 = 0 \), for \( i = N^o + 1, \ldots, N \). Markov's inequality, (23) in Lemma A.4, (34) and (39) ensure that

\[
\Pr \left[ \sup_{1 \leq l_N \leq N, 1 \leq l_T \leq T} \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\| \leq \eta \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \right] \leq \frac{1}{\eta^2} \sum_{l_N=1}^N \sum_{l_T=1}^T \mathbf{E} \left[ \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\|^2 \right] \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \leq \frac{1}{\eta^2} \sum_{l_N=1}^N \sum_{l_T=1}^T \mathbf{E} \left[ \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\|^2 \right] \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \leq \frac{C_3}{\eta^2} \sum_{l_N=1}^N \sum_{l_T=1}^T \mathbf{E} \left[ \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\|^2 \right] \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \leq \frac{C_3}{\eta^2} \sum_{l_N=1}^N \sum_{l_T=1}^T \mathbf{E} \left[ \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\|^2 \right] \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \leq \frac{4C_4}{\eta^2} \sum_{l_N=1}^N \sum_{l_T=1}^T \mathbf{E} \left[ \left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\|^2 \right] \bigg/ \left( \theta_{l_Nl_T} - \theta^0 \right)^2 \leq \frac{4}{(0.5)^2 (0.5)^2} \frac{C_4}{\eta^2} \leq \frac{\varepsilon}{2}.
\]

It follows that for all \( 1 \leq l_N \leq N \) and \( 1 \leq l_T \leq T \), and with probability greater than one \( \varepsilon / 2 \),

\[
\left\| \mathbf{h}^0 (\alpha^0, \theta_{l_Nl_T}) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\| \leq \eta,
\]

which implies that

\[
\Pr \left[ \sup_{\theta_{l_Nl_T} \in (\theta - \theta^0)} \left\| \mathbf{h}^0 (\alpha^0, \theta) - \mathbf{h}^0 (\alpha^0, \theta^0) \right\| \geq \eta \bigg/ \left( \theta - \theta^0 \right)^2 \right] \leq \frac{\varepsilon}{2}.
\]

Taking the infimum over \(-v \left( N^oT \right) \geq (\theta - \theta^0) \geq -B \) allows to prove a similar inequality using the same argument, which completes the proof. \( \blacksquare \)

### A.3 Proof of the Result in Section 4

Given the loss function in (12) and for any fixed \( R \geq 1 \), let \( \mathbf{\hat{A}}_j^R (\theta) = \begin{bmatrix} \mathbf{\hat{X}}_{j1}^R (\theta), \ldots, \mathbf{\hat{X}}_{jN}^R (\theta) \end{bmatrix}' \) be the \( N \times R \) matrix of estimated loadings for fixed \( \theta \), for \( j = 1, 2 \). Let \( \mathbf{\hat{V}}_j^R (\theta) \) be the \( R \times R \) diagonal matrix of the first \( R \) largest eigenvalues of \( \mathbf{\hat{S}}_j^R (\theta) \) in (7) in decreasing order, for \( j = 1, 2 \). Define the \( R^o \times R \) rotation matrix

\[
\mathbf{\hat{R}}_{j}^R (\theta^0) = \frac{\mathbf{F}_j^o (\theta^0) \mathbf{E}_j^o (\theta^0)'}{T} \frac{\mathbf{A}_j^R \mathbf{\hat{A}}_j^R (\theta^0)}{N} \mathbf{\hat{V}}_j^R (\theta^0)^{-1}, \quad j = 1, 2,
\]

where \( \mathbf{F}_j^o (\theta) \) is defined in Section 3.4.

**Lemma A.8** For any fixed \( R \geq 1 \), there exists a \( R^o \times R \) matrix \( \mathbf{\hat{H}}_{j}^R (\theta^0) \) as defined in (40), with\( \text{rank} \left[ \mathbf{\hat{H}}_{j}^R (\theta^0) \right] = \min \{ R^o, R \} \), \( C_{N,T} \) and \( C_{N,T} = \min \left\{ \sqrt{N}, \sqrt{T} \right\} \), such that

\[
C_{N,T}^2 \left[ \frac{1}{N} \sum_{i=1}^N \left\| \mathbf{\hat{X}}_{ji}^R (\theta^0) - \mathbf{\hat{H}}_{ji}^R (\theta^0)' \mathbf{X}_j^o \right\|^2 \right] = O_p(1), \quad j = 1, 2.
\]
Lemma A.9 Let \( \hat{\theta}^R \) be the estimator for \( \theta^0 \) obtained from the loss function in (12) for any a priori chosen number of factors \( R = R^0 \) such that \( R \geq R^0 \). Then under assumptions I, C1-CN and CR,

\[
N^{-\alpha} T ( \hat{\theta}^R - \theta^0 ) = O_p (1) .
\]

Proof of Theorem 4.1. Consider

\[
x_t = I_{11} (\theta^0) \Lambda_{1t}^0 + I_{2t} (\theta^0) \Lambda_{2t}^0 + \epsilon_t = \Lambda^0 [ I_{1t} (\theta^0) \mathbf{f}_t^0, I_{2t} (\theta^0) \mathbf{f}_t^0 ]' + \epsilon_t,
\]

where \( \Lambda^0 = (\Lambda_{11}^0, \Lambda_{21}^0)' \) is a \( N \times 2R^0 \) matrix, with \( \lambda_{1t}^0 = (\lambda_{11t}^0, \lambda_{21t}^0)' \) a \( 2R^0 \times 1 \) vector, and \( [ I_{1t} (\theta^0) \mathbf{f}_t^0, I_{2t} (\theta^0) \mathbf{f}_t^0 ]' \) is a \( 2R^0 \times 1 \) vector. Given the loss function in (12), let \( \tilde{\mathbf{f}}_t^R (\theta) \) be the \( R \times 1 \) vector of estimated factors for fixed \( \theta \), for \( t = 1, \ldots, T \). Further, let \( \tilde{\mathbf{H}}_{j+t}^{R+} (\theta^0) \) be the generalized inverse of \( \tilde{\mathbf{H}}_{j+t}^R (\theta^0) \) in (40) such that \( \tilde{\mathbf{H}}_{j+t}^{R+} (\theta^0) \tilde{\mathbf{H}}_{j+t}^R (\theta^0) = I_R \), for \( j = 1, 2 \). Lemma A.8 implies that

\[
C_{NT}^2 \left\{ \frac{1}{T} \sum_{t=1}^T \left\| \tilde{\mathbf{f}}_t^R (\theta^0) - \left[ I_{1t} (\theta^0) \tilde{\mathbf{H}}_{11+t}^{R+} (\theta^0) + I_{2t} (\theta^0) \tilde{\mathbf{H}}_{22+t}^{R+} (\theta^0) \right] \tilde{\mathbf{f}}_t^0 \right\|^2 \right\} = O_p (1)
\]

or

\[
C_{NT}^2 \left\{ \frac{1}{T} \sum_{t=1}^T \left\| \left[ \begin{array}{c} I_{1t} (\theta^0) \tilde{\mathbf{f}}_t^R (\theta^0) \\ I_{2t} (\theta^0) \tilde{\mathbf{f}}_t^R (\theta^0) \end{array} \right] - \left[ \begin{array}{c} I_{1t} (\theta^0) \tilde{\mathbf{H}}_{11+t}^{R+} (\theta^0) \tilde{\mathbf{f}}_t^0 \\ I_{2t} (\theta^0) \tilde{\mathbf{H}}_{22+t}^{R+} (\theta^0) \tilde{\mathbf{f}}_t^0 \end{array} \right] \right\|^2 \right\} = O_p (1),
\]

so that by Lemma A.9

\[
C_{NT}^2 \left\{ \frac{1}{T} \sum_{t=1}^T \left\| \left[ \begin{array}{c} I_{1t} (\theta^R) \tilde{\mathbf{f}}_t^R (\theta^R) \\ I_{2t} (\theta^R) \tilde{\mathbf{f}}_t^R (\theta^R) \end{array} \right] - \left[ \begin{array}{c} I_{1t} (\theta^R) \tilde{\mathbf{H}}_{11+t}^{R+} (\theta^R) \tilde{\mathbf{f}}_t^0 \\ I_{2t} (\theta^R) \tilde{\mathbf{H}}_{22+t}^{R+} (\theta^R) \tilde{\mathbf{f}}_t^0 \end{array} \right] \right\|^2 \right\} = O_p (1),
\]

which is analogous to Theorem 1 and Corollary 2 in Bai and Ng (2002): this is sufficient to complete the proof of the theorem, as it shows that the criteria in (13) select \( \{ R^0 + R^0 \} \) factors.

Proof of Lemma A.8. The proof of Lemma A.8 is similar to that of Theorem 3.2 and omitted. ■

Proof of Lemma A.9. Given the loss function in (12) and following similar steps as in the proof of Theorem 3.3, it can be shown that

\[
\lim_{N,T \to \infty} \mathbb{P} \left\{ S \left[ \mathbf{A}^R (\theta^0), \mathbf{F}^R (\theta^0) \right] \leq S \left[ \mathbf{A} (\theta^0), \mathbf{F} (\theta^0) \right] \right\} = 0, \quad \forall \theta \neq \theta^0, \quad R^0 \leq R \leq R^{\max} .
\]

In order to prove the lemma it is then sufficient to show that

\[
S \left[ \mathbf{A}^R (\theta^0), \mathbf{F}^R (\theta^0) \right] - S \left[ \mathbf{A} (\theta^0), \mathbf{F} (\theta^0) \right] = O_p \left( C_{NT}^2 \right)
\]

for any fixed \( R \) such that \( R^0 \leq R \leq R^{\max} \), where \( S \left[ \mathbf{A} (\theta), \mathbf{F} (\theta) \right] = S \left[ \mathbf{A}^{R^0} (\theta), \mathbf{F}^{R^0} (\theta) \right] \). Notice that

\[
S \left[ \mathbf{A}^R (\theta^0), \mathbf{F}^R (\theta^0) \right] - S \left[ \mathbf{A} (\theta^0), \mathbf{F} (\theta^0) \right] \leq 2 \max_{R^0 \leq R \leq R^{\max}} S \left[ \mathbf{A}^R (\theta^0), \mathbf{F}^R (\theta^0) \right] - S \left[ \mathbf{A} (\theta^0), \mathbf{F} (\theta^0) \right] ;
\]
it therefore is sufficient to show that

\[ S \left[ \hat{A}^R (\theta^0), \hat{F}^R (\theta^0), \theta^0 \right] - S (A^0, F^0, \theta^0) = O_p \left( C_{NT}^{-2} \right) \]

for each \( R \) such that \( R^0 \leq R \leq R_{\max} \). We have

\[
x_t = \mathbb{I}_{11} (\theta^0) A^H_1 t^H_1 + \mathbb{I}_{2t} (\theta^0) A^H_2 t^H_2 + e_t
\]

\[
= \mathbb{I}_{11} (\theta^0) A^H_1 \hat{H}^H_{11} (\theta^0) \hat{H}^H_{11} (\theta^0) t^H_1 + \mathbb{I}_{2t} (\theta^0) A^H_2 \hat{H}^H_{22} (\theta^0) \hat{H}^H_{22} (\theta^0) t^H_2 + e_t,
\]

where \( \hat{H}^H_{jj} (\theta^0) \) is defined in the proof of Theorem 4.1, for \( j = 1, 2 \). This implies

\[
x_t = 1_{1t} (\theta^0) \hat{A}^R_1 (\theta^0) \hat{H}^R_{11} (\theta^0) t^H_1 + \mathbb{I}_{2t} (\theta^0) \hat{A}^R_2 (\theta^0) \hat{H}^R_{22} (\theta^0) t^H_2
\]

\[
+ e_t = 1_{1t} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{11} (\theta^0) t^H_1 + \mathbb{I}_{2t} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{22} (\theta^0) t^H_2 - \mathbb{I}_{11} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{11} (\theta^0) t^H_1 - \mathbb{I}_{22} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{22} (\theta^0) t^H_2 + e_t,
\]

where

\[
u_t = e_t - \mathbb{I}_{11} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{11} (\theta^0) t^H_1 - \mathbb{I}_{22} (\theta^0) \left[ \hat{A}^R (\theta^0) - A^0 \right] \hat{H}^R_{22} (\theta^0) t^H_2.
\]

Notice that

\[ S (A^0, F^0, \theta^0) = (NT)^{-1} \sum_{t=1}^{T} e_t e_t \]

and

\[
S \left[ \hat{A}^R (\theta^0), \hat{F}^R (\theta^0), \theta^0 \right] = (NT)^{-1} \sum_{t=1}^{T} u_t^H \nu_t
\]

\[
= (NT)^{-1} \sum_{t=1}^{T} e_t e_t
\]

\[
-2 (NT)^{-1} \sum_{t=1}^{T} e_t^H \nu_t
\]

\[
= (NT)^{-1} \sum_{t=1}^{T} e_t e_t
\]

\[
\text{so that}
\]

\[
\left| S \left[ \hat{A}^R (\theta^0), \hat{F}^R (\theta^0), \theta^0 \right] - S (A^0, F^0, \theta^0) \right| \leq S^{(1)} \left[ \hat{A}^R (\theta^0), \hat{F}^R (\theta^0), \theta^0 \right] + S^{(2)} \left[ \hat{A}^R (\theta^0), \hat{F}^R (\theta^0), \theta^0 \right].
\]
For any $A \times A$ matrix $A$, $|\text{tr}(A)| \leq \|A\|$. It follows that

\[
\begin{align*}
|S^{(1)}[\tilde{A}^R (\theta^0), \tilde{F}^R (\theta^0), \theta^0]| &= \text{tr} \left\{ S^{(1)}[\tilde{A}^R (\theta^0), \tilde{F}^R (\theta^0), \theta^0] \right\} \\
&= 2 \text{tr} \left\{ (NT)^{-1} \sum_{t=1}^{T} F^0_t \left\{ I_{1t} (\theta^0) \tilde{H}^{R+}_{11} (\theta^0)' \left[ \tilde{A}^R (\theta^0) - \Lambda t \tilde{H}^{R+}_{11} (\theta^0) \right]' \right\} \right\} \\
&\leq 2R \left\{ \|\tilde{H}^{R+}_{11} (\theta^0)\| \left[ \frac{1}{N} \sum_{i=1}^{N} \|\Lambda^R_{1i} (\theta^0) - \Lambda t \tilde{H}^{R+}_{11} (\theta^0)\|_1 \right] \right\}^{1/2} \left\{ \frac{1}{\sqrt{T}} \left[ \frac{1}{N} \sum_{i=1}^{N} \|I_{1t} (\theta^0) \|_1 \right] \right\}^{1/2} \\
&= O_p \left( C^{-2}_{N^2T} \right) + O_p \left( C^{-2}_{N^2T} \right) = O_p \left( C^{-2}_{N^2T} \right)
\end{align*}
\]

by Assumption C.4 and Lemma A.8. Further, by Lemma A.8

\[
|S^{(2)}[\tilde{A}^R (\theta^0), \tilde{F}^R (\theta^0), \theta^0]| = S^{(2)}[\tilde{A}^R (\theta^0), \tilde{F}^R (\theta^0), \theta^0] \\
&\leq \left[ \frac{1}{N} \sum_{i=1}^{N} \|\Lambda^R_{1i} (\theta^0) - \Lambda t \tilde{H}^{R+}_{11} (\theta^0)\|_1 \right] \left[ \frac{1}{T} \sum_{t=1}^{T} \|I_{1t} (\theta^0) \|_1 \right] \\
&\leq O_p (1) \cdot \left[ O_p \left( C^{-2}_{N^2T} \right) \cdot O_p (1) + O_p \left( C^{-2}_{N^2T} \right) \cdot O_p (1) \right] = O_p \left( C^{-2}_{N^2T} \right),
\]

which completes the proof of the lemma. \( \blacksquare \)

**A.4 Proofs of the Result in Section 5.2**

Under Assumption LT1, $\left( T^{-1} \sum_{t=1}^{T} \|\tilde{f} - \tilde{H}^{-1} \tilde{f}^0\|_2^2 \right) = O_p \left( C^{-2}_{N^2T} \right)$, with $\tilde{H}^1_1$ as in Theorem 3.1. Let $\tilde{f}^1$ be the first $1 \times R^0$ row vector of $\tilde{H}^{-1}$. and $\tilde{H}^1$ be the $(R^0 - 1) \times R^0$ matrix containing the second to last row of $\tilde{H}^{-1}$. We have

\[
\tilde{f}^1 = \begin{pmatrix} \tilde{f}_{11} & \vdots & \tilde{f}_{1T} \end{pmatrix} = \begin{pmatrix} \tilde{f}^0_1 & \tilde{f}^0_2 & \tilde{f}^0_3 & \cdots & \tilde{f}^0_T \end{pmatrix} = \tilde{f}^0.
\]

Define $\tilde{f}^{+0}_{-1,t}(\theta) = \left[ I_{1t} (\theta) \tilde{f}^0_{-1,1} + I_{2t} (\theta) \tilde{f}^0_{-1,1} \right]'$.

**Lemma A.10** For each $\theta$,

\[
\left\| \frac{1}{T} \sum_{t=1}^{T} I_{1t} (\theta) \tilde{f} \tilde{f}^0 - \frac{1}{T} \sum_{t=1}^{T} I_{2t} (\theta) \tilde{f}^{+0} \tilde{f}^0 \right\| = O_p \left( C^{-2}_{N^2T} \right), \quad j = 1, 2.
\]

**Lemma A.11** For each $\theta$,

\[
\left\| \frac{1}{T} \sum_{t=1}^{T} \tilde{f}_{-1,t} (\theta) \tilde{f}_{11} - \frac{1}{T} \sum_{t=1}^{T} \tilde{f}^{+0}_{-1,t} (\theta) \tilde{f}^{+0}_{11} \right\| = o_p (1).
\]

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Proof of Theorem 5.1. From Theorem 3.1, \( \hat{H}_1 = (\mathbf{F}_0^{0\ast} / T) (A_0^{0\ast} \hat{A}_1 / N) \), where \( A_0^{0\ast} \) is an invertible matrix and it is unique by Assumption LT3. By Lemma A.3 in Bai (2003), \( \left( A_0^{0\ast} \hat{A}_1 / N \right) \equiv Q_{A_1} \), where \( Q_{A_1} \) is an invertible matrix and it is unique by Assumption LT3. Let \( h_1^{0\ast} \) be the first \( 1 \times R^0 \) row vector of \( (H_1)^{-1} \). Let \( H_1^{0\ast} \) be the \( (R^0 - 1) \times R^0 \) matrix containing the second to last row of \( (H_1)^{-1} \). Define \( f_{1t}^{0\ast} = h_1^{0\ast} f_{1t}^0 \), \( f_{-1,t}^{0\ast} = H_1^{0\ast} f_{1t}^0 \) and \( f_{-1,t}^{0\ast} \) \( (\theta) = \left[ \bar{I}_{11} (\theta) f_{-1,1t}^{0\ast}, \bar{I}_{22} (\theta) f_{-1,2t}^{0\ast} \right] ^\prime \). From Lemma A.11 it follows that

\[
\left\| \frac{1}{\sqrt{T}} \sum_{t=1}^T \bar{f}_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} - \frac{1}{\sqrt{T}} \sum_{t=1}^T \bar{f}_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| = o_p (1).
\]

In order to prove that \( \hat{k}_- (\theta) \Rightarrow k_0^0 (\theta) \) it is sufficient to prove that \( T^{-1/2} \sum_{t=1}^T f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \Rightarrow k_0^0 (\theta) \): this follows if \( T^{-1/2} \sum_{t=1}^T f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \) is stochastically equicontinuous. As in Hansen (1996), we resort to Application 4 of Theorem 1 in Doukhan et al. (1995). Under Assumption LT5(a), the summands \( k_{-1,t}^{0\ast} (\theta) = f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \) satisfy the required \( \beta \)–mixing decay rate. Since \( \left\| H_1^{0\ast} \right\| = O (1) \) and \( \left\| h_1^{0\ast} \right\| = O (1) \), the envelope function \( \sup_{\theta} \left\| k_{-1,t}^{0\ast} (\theta) \right\| \) satisfies

\[
\sup_{\theta} \left\| k_{-1,t}^{0\ast} (\theta) \right\| = \sup_{\theta} \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| = \sup_{\theta} \left\| \left[ I_{11} (\theta) H_1^{0\ast} f_{1t}^0 \right] ^\prime, \left[ I_{22} (\theta) H_1^{0\ast} f_{1t}^0 \right] ^\prime \right\| H_1^{0\ast} \left[ I_{11} (\theta) f_{1t}^0 + I_{22} (\theta) f_{1t}^0 \right] ^\prime \leq \sup_{\theta} \left\| I_{11} (\theta) f_{1t}^0 + I_{22} (\theta) f_{1t}^0 \right\| O(1) \leq \sup_{\theta} \left\| I_{11} (\theta) f_{1t}^0 \right\| + \sup_{\theta} \left\| I_{22} (\theta) f_{1t}^0 \right\| O(1)
\]

the envelope function is \( L_{2\xi} \) bounded since by Schwarz’s inequality and Assumption LT5(b)

\[
E \left[ \max_{j=1,2} \left\{ \sup_{\theta} \left\| I_{jt} (\theta) f_{1t}^0 \right\| \right\} \cdot \max_{j=1,2} \left\{ \sup_{\theta} \left\| I_{jt} (\theta) f_{1t}^0 \right\| \right\} \right] ^{2\xi} \leq \left\{ E \left[ \max_{j=1,2} \left\{ \sup_{\theta} \left\| I_{jt} (\theta) f_{1t}^0 \right\| \right\} \right] ^{4\xi} \right\} ^{1/2} \leq \left\{ E \left[ \max_{j=1,2} \left\{ \sup_{\theta} \left\| I_{jt} (\theta) f_{1t}^0 \right\| \right\} \right] ^{4\xi} \right\} ^{1/2} < \infty.
\]

We then need to show that the log of the \( L_{2\xi} \) bracketing numbers \( N (\zeta) \) is integrable. For some \( G < \infty \) and for all \( \theta \), there is some \( \bar{\theta} \) such that \( \| \theta - \bar{\theta} \| \leq G \cdot N (\zeta) ^{-1/\gamma} \). Set \( N (\zeta) = M^{1/\gamma} G \zeta^{-1/\gamma} \) and notice that

\[
E \left[ \left\| k_{-1,t}^{0\ast} (\theta) - k_{-1,t}^{0\ast} (\bar{\theta}) \right\| ^{2\xi} \right] ^{1/(2\xi)} = E \left[ \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} - f_{-1,t}^{0\ast} (\bar{\theta}) f_{1t}^{0\ast} \right\| ^{2\xi} \right] ^{1/(2\xi)} \leq \left\{ E \left[ \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| \right] ^{2\xi} \right\} ^{1/(2\xi)} \leq \left\{ E \left[ \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| \right] ^{2\xi} \right\} ^{1/(2\xi)} \leq \left\{ E \left[ \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| \right] ^{2\xi} \right\} ^{1/(2\xi)} \leq \left\{ E \left[ \left\| f_{-1,t}^{0\ast} (\theta) f_{1t}^{0\ast} \right\| \right] ^{2\xi} \right\} ^{1/(2\xi)} O (1).
\]
By Assumption LT6,

$$\left\{ \mathbb{E} \left[ \max_{j=1}^k \| [l_{jt}(\vartheta) - l_{jt}(\tilde{\vartheta})]^\prime \xi^\prime \|^{2\gamma} \right] \right\}^{1/(2\gamma)} \leq M \cdot |\vartheta - \tilde{\vartheta}| \gamma \leq M \cdot G^\gamma \cdot N(\zeta)^{-\gamma} = \zeta,$$

so that $N(\zeta)$ satisfies the definition of bracketing numbers: the log of $N(\zeta)$ may be shown to be integrable as in the proof of Theorem 1 in Hansen (1996). It follows that $T^{-1/2} \sum_{t=1}^T f_t^0(\vartheta) f_t^0(\vartheta)$ is stochastically equicontinuous and then $k_-(\vartheta) \Rightarrow k^0(\vartheta)$. Let $o_{(R^0 - 1) \times R^0}$ be the $(R^0 - 1) \times R^0$ zero matrix. Notice that

$$\tilde{M}_-(\theta_1, \theta_2) = T^{-1} \sum_{t=1}^T \tilde{f}_t(\theta_1) \tilde{f}_t(\theta_2)^\prime$$

$$= T^{-1} \sum_{t=1}^T \left\{ \begin{array}{c} l_{1t}(\theta_1) \tilde{f}_{1t}(\theta_1) \\ l_{2t}(\theta_1) \tilde{f}_{2t}(\theta_1) \\ \vdots \\ l_{2t}(\theta_2) \tilde{f}_{2t}(\theta_2) \\ \vdots \\ l_{1t}(\theta_2) \tilde{f}_{1t}(\theta_2) \\ l_{2t}(\theta_2) \tilde{f}_{2t}(\theta_2) \end{array} \right\}$$

$$= T^{-1} \sum_{t=1}^T \left\{ \begin{array}{c} l_{1t}(\theta_1) \left[ H_1^0 f_t^0 + o_p(1) \right] \\ l_{2t}(\theta_1) \left[ H_2^0 f_t^0 + o_p(1) \right] \\ \vdots \\ l_{1t}(\theta_2) \left[ H_1^0 f_t^0 + o_p(1) \right] \\ l_{2t}(\theta_2) \left[ H_2^0 f_t^0 + o_p(1) \right] \end{array} \right\}$$

$$= \left[ \begin{array}{cc} H_1^0 & 0 \end{array} \right] \left[ \begin{array}{c} \tilde{M}_0(\theta_1, \theta_2) \\ 0_{(R^0 - 1) \times R^0} \end{array} \right],$$

uniformly in $(\theta_1, \theta_2)$ by Assumption LT7, where

$$\tilde{M}_0(\theta_1, \theta_2) = \left[ \begin{array}{cc} H_1^0 & 0 \end{array} \right] \left[ \begin{array}{c} \tilde{M}_0(\theta_1, \theta_2) \\ 0_{(R^0 - 1) \times R^0} \end{array} \right].$$

The proof of the theorem is completed following similar steps as in the proof of Theorem 1 in Hansen (1996). □

**Proof of Lemma A.10.** The proof is similar to that of Lemma 10 in Chen et al. (2014) and omitted. □

**Proof of Lemma A.11.** The proof follows from Lemma A.10 and Assumption LT4. □

**References**


This table presents results for the estimator for $\theta = 2$. The DGP is detailed in Section 6.1. CSI denotes time homoskedastic factors and idiosyncratic components, and cross-sectionally independent idiosyncratic components. CSD denotes time homoskedastic factors and idiosyncratic components, and cross-sectionally dependent idiosyncratic components. CSDH denotes time heteroskedastic factors and idiosyncratic components, and cross-sectionally dependent idiosyncratic components.

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Panel B: $a^0 = 1.00$

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Table 2: MSE in the case of the Estimator for \( \hat{c}_t \)

This table presents results for the estimator for

\[
\hat{c}_t = I(z_t^1 \leq \theta^0) \lambda_{1t}^1 \rho_{1t} + I(z_t^1 > \theta^0) \lambda_{2t} \rho_{2t}, \quad i = 1, \ldots, N, \quad t = 1, \ldots, T.
\]

The DGP is the same as in Table 1. CSI, CSD and CSDH denote the same scenarios as in Table 1.

Panel A: \( \alpha^2 = 0.60 \)

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Panel B: \( \alpha^2 = 1.00 \)

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Table 3: Model Selection Criteria, $R^2 = 2$, $\alpha^2 = 0.60$

This table presents results for the model selection criteria in (13). The DGP is detailed in Section 6.2. CSI, CSD and CSDH denote the same scenarios as in Table 1.

### Panel A: $IC_{31}(R, R)$

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### Panel B: $IC_{22}(R, R)$

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### Panel C: $IC_{33}(R, R)$

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Table 4: Linearity Test, $\alpha = 0.60$

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<td>0.0295</td>
<td>0.0280</td>
<td>0.0440</td>
<td>0.0335</td>
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<tr>
<td>CSD</td>
<td>0.0245</td>
<td>0.0085</td>
<td>0.0095</td>
<td>0.0245</td>
<td>0.0240</td>
<td>0.0285</td>
<td>0.0485</td>
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<tr>
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<td>0.0095</td>
<td>0.0100</td>
<td>0.0285</td>
<td>0.0220</td>
<td>0.0755</td>
<td>0.0485</td>
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<tr>
<td>$\rho_f$ &gt; 0</td>
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<td>0.0610</td>
<td>0.0735</td>
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<td>0.0635</td>
<td>0.0670</td>
<td>0.0665</td>
<td>0.0980</td>
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Table 5: Empirical Application, Estimation Results, 1985 - 2014
This table presents results from the empirical application of the model in (1). The vector $x_t$ is made of the 147 updated monthly financial variables employed in Jurado et al. (2015). The threshold variable $z_t$ is the lagged index of economic policy uncertainty proposed in Baker et al. (2016). The model is estimated over the period 1985:01 – 2014:12, a total of 360 observations. $\hat{\theta}$ is the point estimate of the threshold parameter $\theta^0$ and $\hat{\pi} = \frac{1}{T} \sum_{t=1}^{T} I(z_t \leq \hat{\theta})$. The optimal number of factors $\hat{R}$ is estimated according to the selection criteria $IC_{p_1}(R, R)$, $IC_{p_2}(R, R)$ and $IC_{p_3}(R, R)$ in (13). The connectedness measures $C_1(\hat{R})$ and $C_2(\hat{R})$ are as in (20).

<table>
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<tr>
<th>$\theta$</th>
<th>$1 - \hat{\pi}$</th>
<th>$\hat{\pi}$</th>
<th>$IC_{p_1}(R, R)$</th>
<th>$IC_{p_2}(R, R)$</th>
<th>$IC_{p_3}(R, R)$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\hat{\theta}$</td>
<td>131.413</td>
<td>0.783</td>
<td>0.217</td>
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<td>$\hat{R}$</td>
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<td>3</td>
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<tr>
<td>$C_1(\hat{R})$</td>
<td>0.678</td>
<td>0.678</td>
<td>0.736</td>
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<tr>
<td>$C_2(\hat{R})$</td>
<td>0.865</td>
<td>0.865</td>
<td>0.898</td>
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</tr>
</tbody>
</table>

Figure 1: Empirical Application, High Economic Policy Uncertainty Regime, 1985 - 2014
This figure shows the high economic policy uncertainty regime, as identified by the sequence $\left\{ 1\left(z_t > \hat{\theta}\right) = 1 \right\}_{t=1}^{T}$, where $\hat{\theta} = 131.413$ is the point estimate of the threshold parameter $\theta^0$. 